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Experiments and Modelling of Electrospinning Process

NANOFIBRES

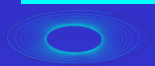
Nanofibres background

1. Nanofibres properties

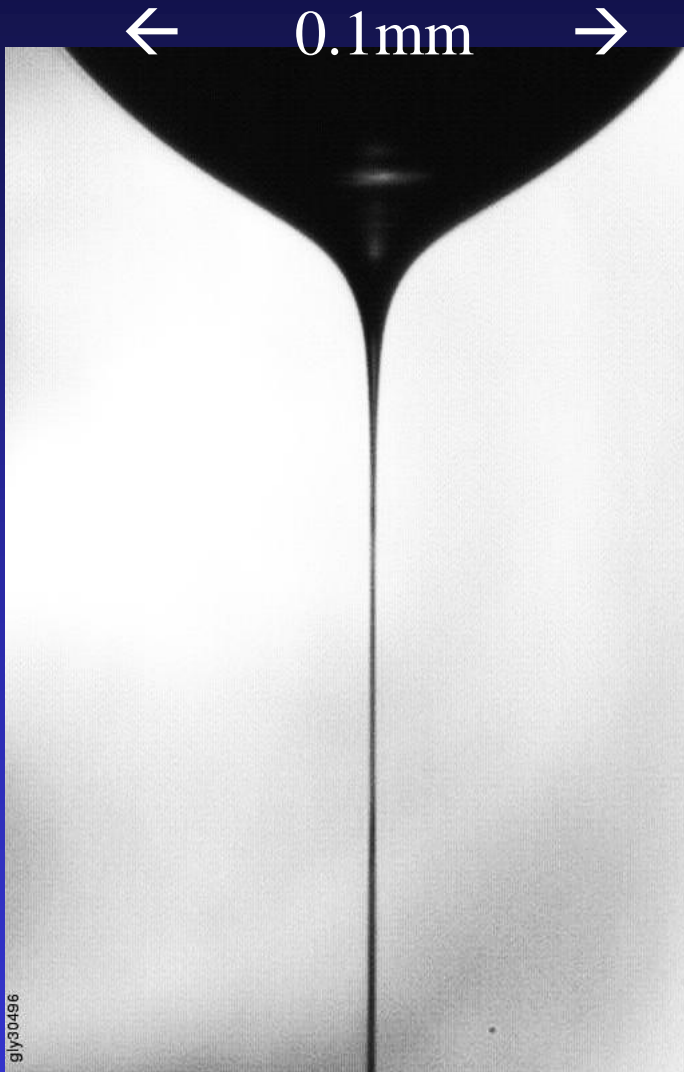
- Increase of the surface to volume ratio -> solar and light sails and mirrors in space
- Reduction of characteristic dimension -> nano-biotechnology, tissue engineering, chemical catalysts, electronic devices
- Bio-active fibres: catalysis of tissue cells growth
- Mechanical properties improvement -> new materials and composite materials by alignment in arrays and ropes

2. Nanofibres production:

- Air-blast atomisation
- Pulling from melts
- **Electrospinning of polymer solutions**



Classical liquid jet



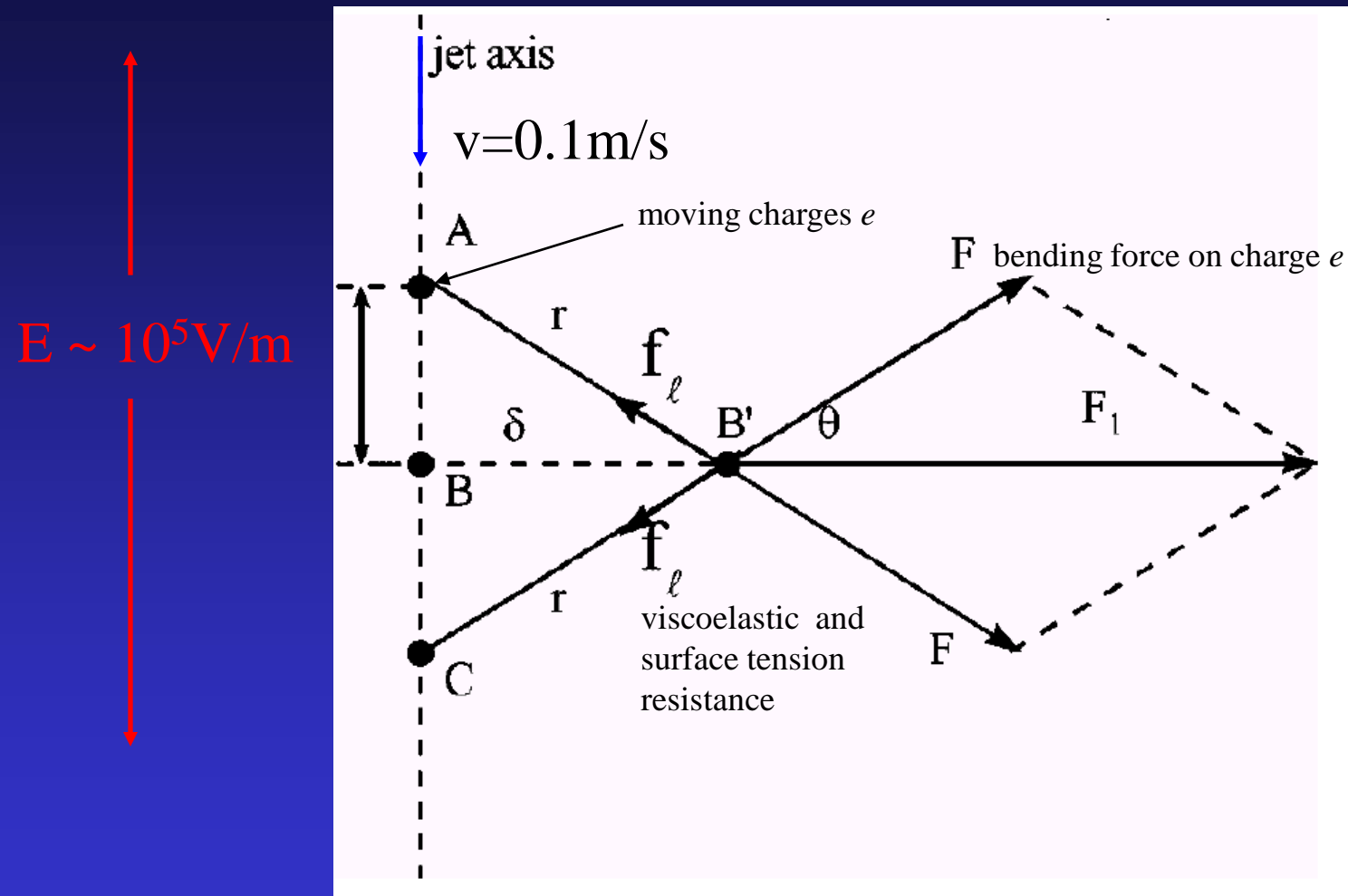
Orifice – 0.1mm

Primary jet diameter $\sim 0.2\text{mm}$

Micro-jet diameter $\sim 0.005\text{mm}$

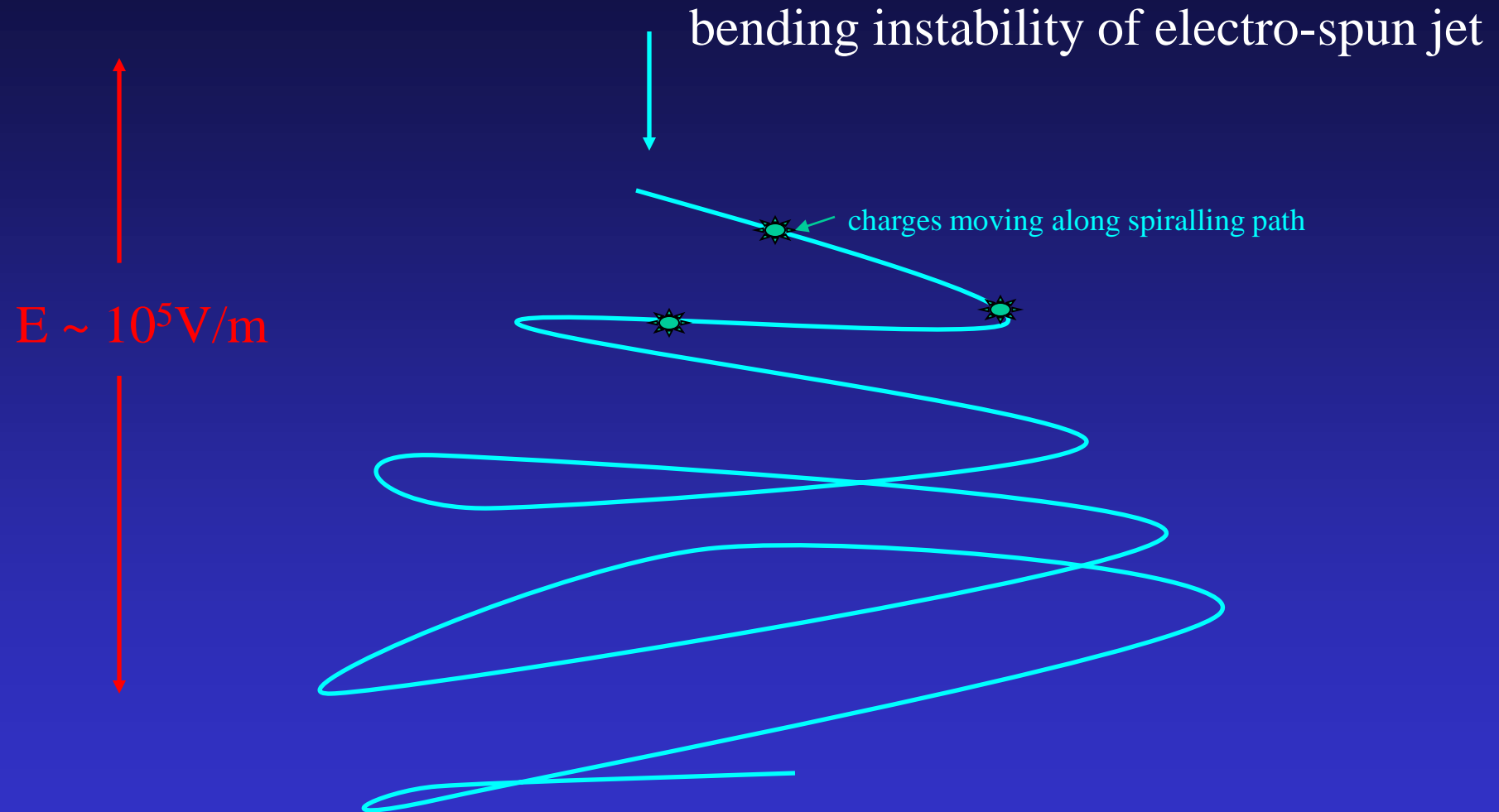
- Gravitational, mechanical or electrostatic pulling limited to $l/d \sim 1000$ by capillary instability
- To reach nano-range:
 - jet thinning $\sim 10^{-3}$
 - draw ratio $\sim 10^6$!

Electro-spinning

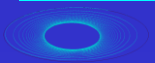


Moving charges (ions) interacting with electrostatic field amplify bending instability, surface tension and viscoelasticity counteract these forces

Electro-spinning



Bending instability enormously increases path of the jet, allowing to solve problem: how to decrease jet diameter 1000 times or more without increasing distance to tenths of kilometres



Electro-spinning

Simple model for elongating viscoelastic thread

$$\frac{d\sigma}{dt} = G \frac{d\ell}{\ell dt} - \frac{G}{\mu} \sigma$$

Stress balance: μ - viscosity, G – elastic modulus stress, σ stress tensor, $d\ell/dt$ – thread elongation

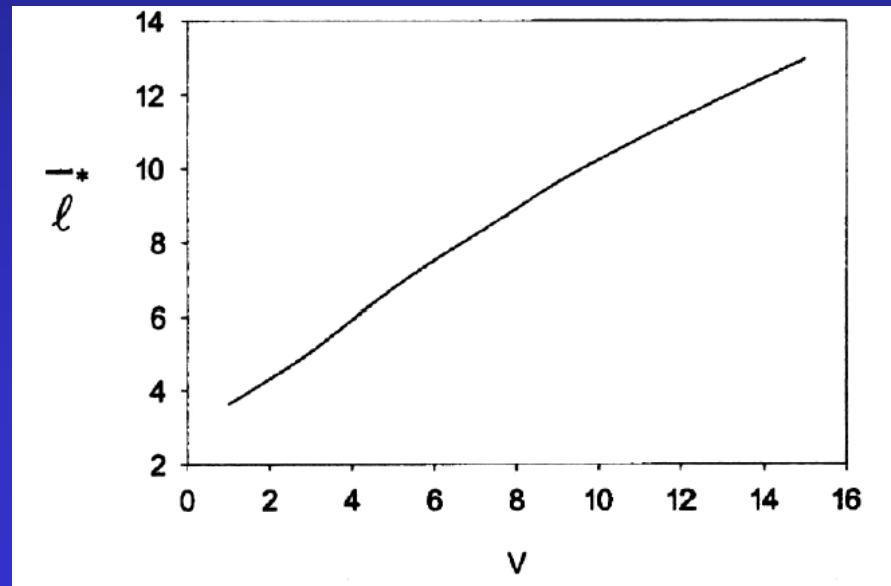
$$m \frac{dv}{dt} = -\frac{e^2}{\ell^2} - \frac{eV_0}{h} + \pi a^2 \sigma$$

Momentum balance: V_0 – voltage, e – charge, a – thread radius, h - distance pipette-collector

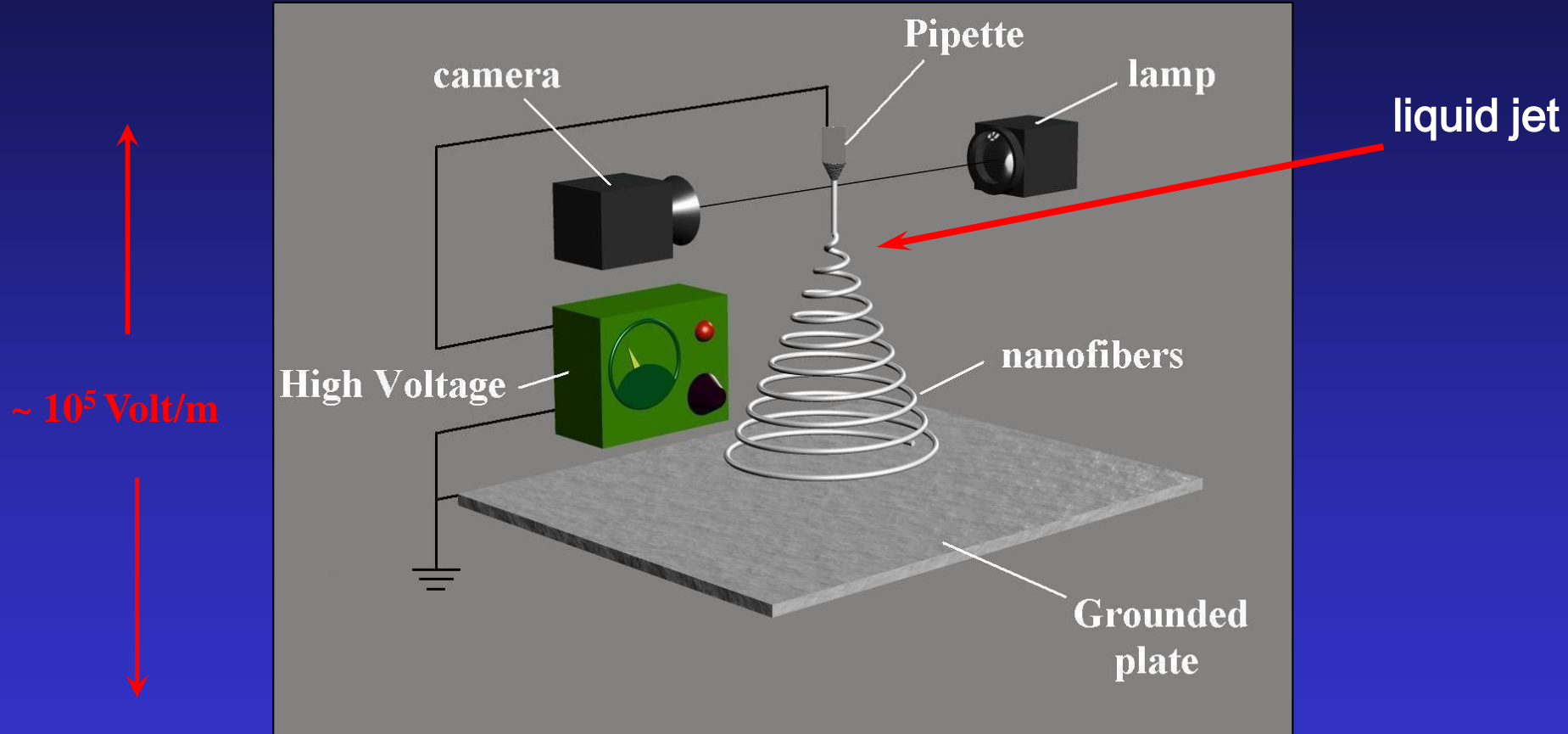
$$\frac{d\ell}{dt} = -v$$

Kinematic condition for thread velocity v

Non-dimensional length of the thread as a function of electrostatic potential



Nanofibres – basic setup



Nanofibres – howto?

1. Viscoelastic fluid:

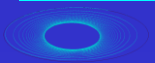
- Dilute solution (4 – 6)% of polyethylene oxide (molar weight $4 \cdot 10^5$ g/mol), in 40% ethanol –water solvent

2. Electrostatic field

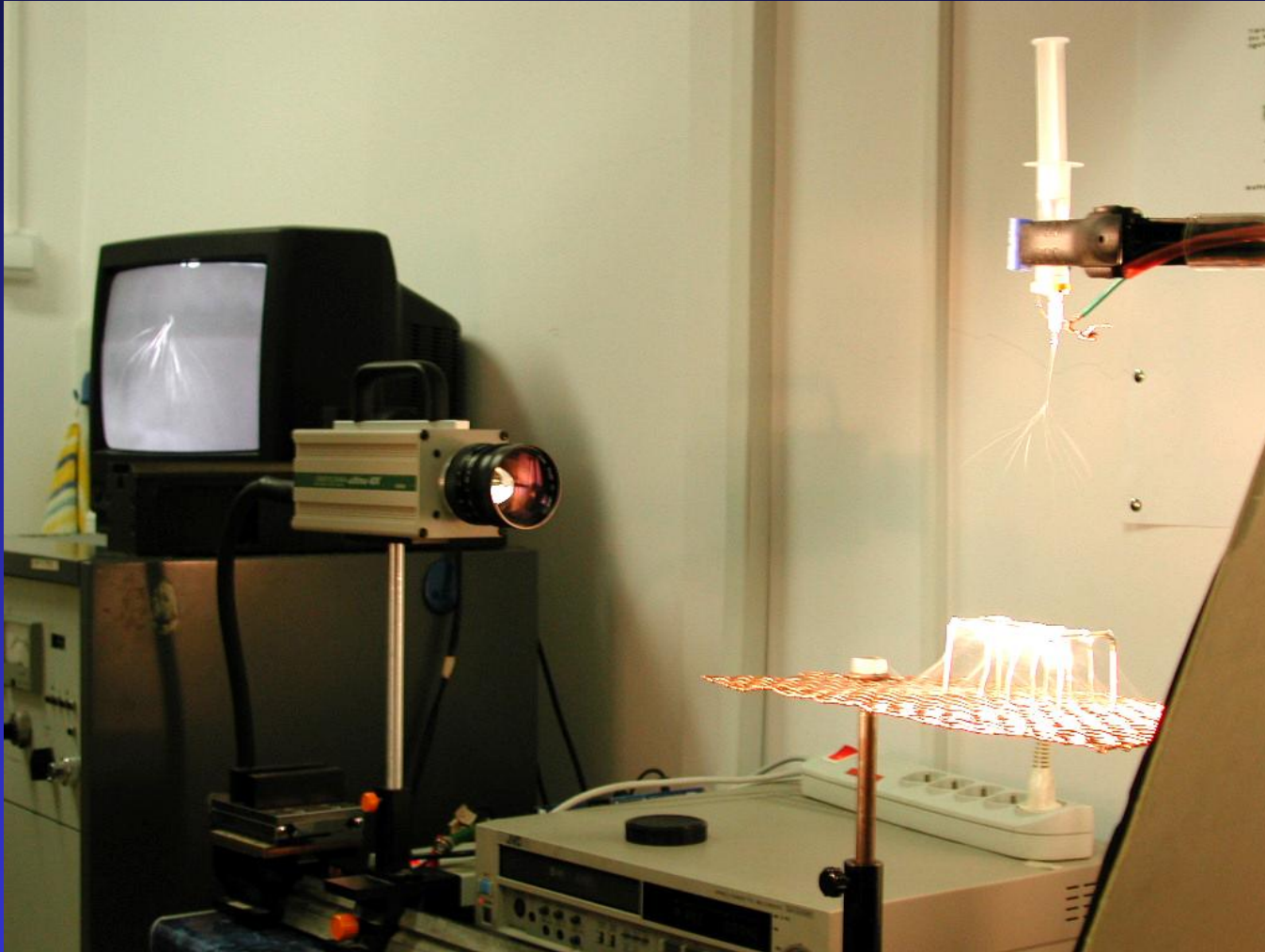
- high voltage power supply (5-30kV)
- plastic syringe
- metal grid to collect fibres

3. Visualization

- high speed camera (4000 – 40000 fps)
- high resolution „PIV” camera (1280x1024pixels)
- CW Argon laser, double pulse Nd:Yag laser, projection lens



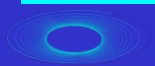
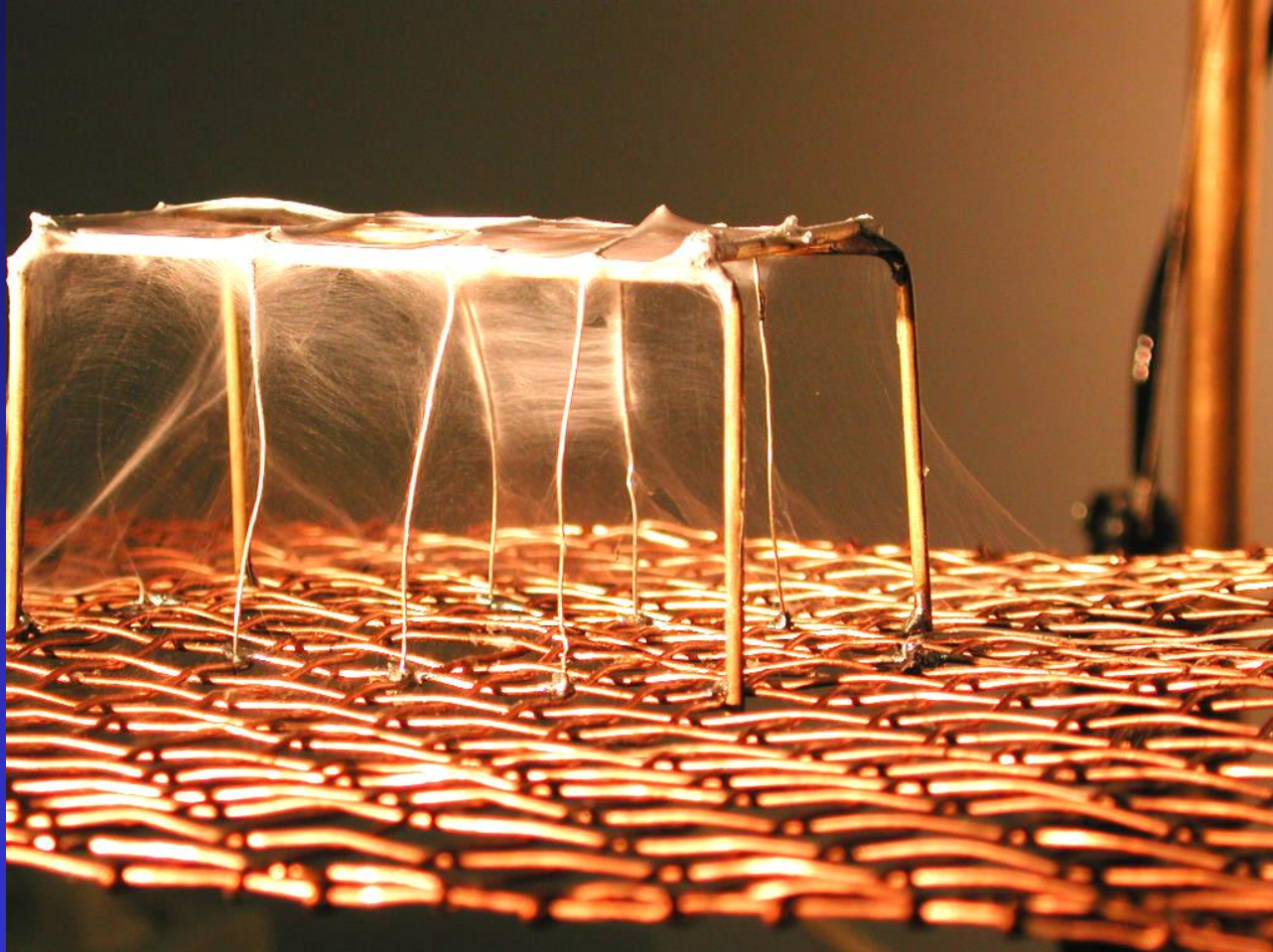
Nanofibres – basic setup



Nanofibres collection

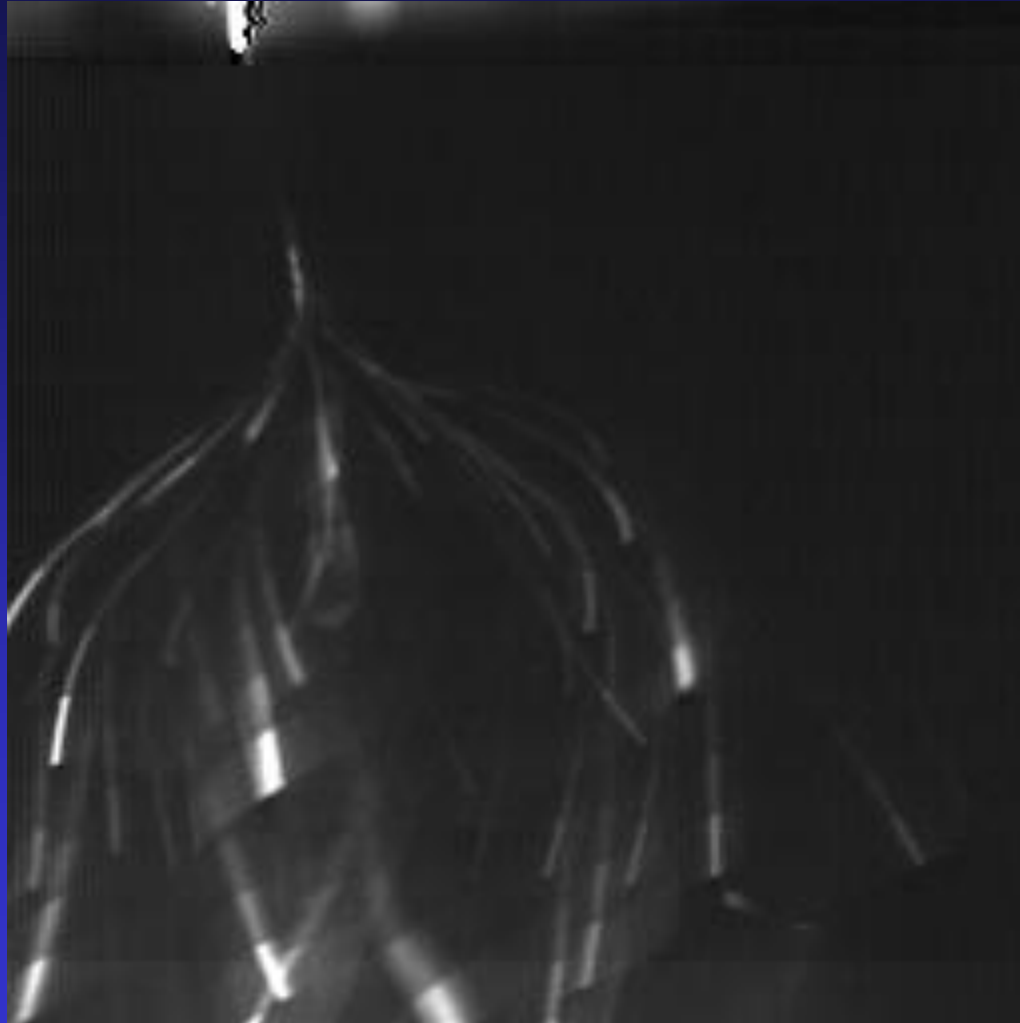


Nanofibres collection

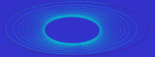


Electrospinning observed at 30fps

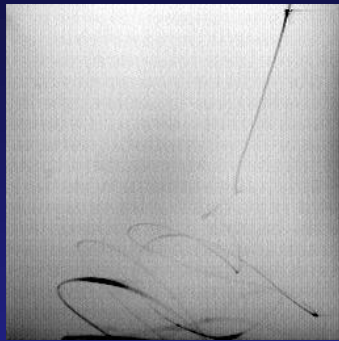
5 cm



Average
velocity of the
fibres: 2 m/s



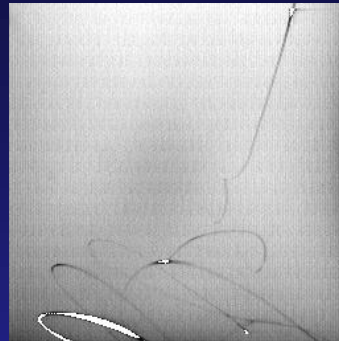
Electrospinning observed at 4500fps



0.0 ms



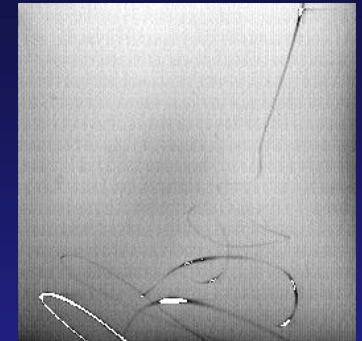
8.9 ms



17.8 ms



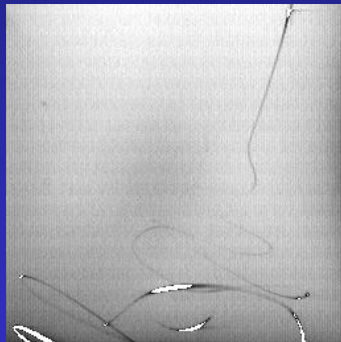
26.7 ms



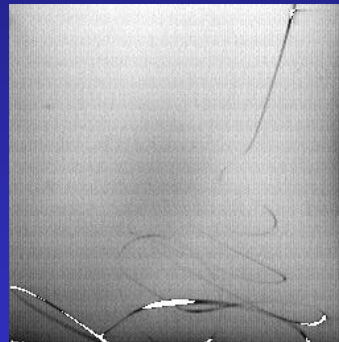
35.6 ms



44.4 ms



53.3 ms



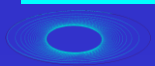
62.2 ms



71.1 ms

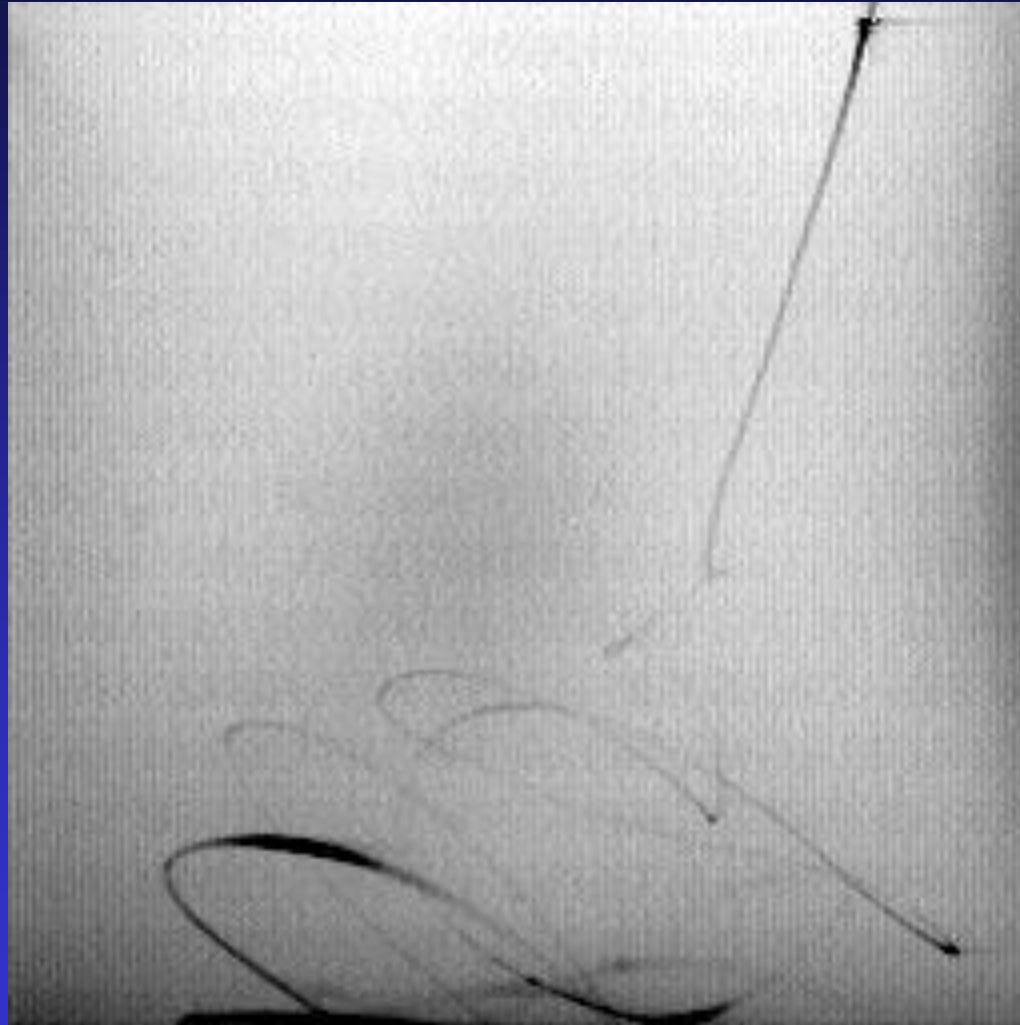


80.0 ms

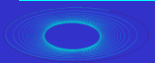


Electrospinning observed at 4500fps

5 cm



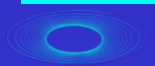
Average
velocity of the
fibre: 2 m/s



Electron microscopy



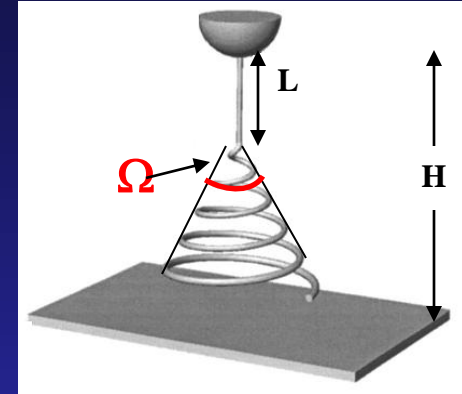
PEO nanofibres



Parametric study

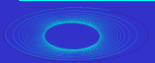
Model validation varying following parameters:

- L – length of the rectilinear part
- Ω – angle of the envelope cone (image analysis)
- U – velocity of the fibre by PIV method
- a – fibre diameter (image analysis)
- structure of collected woven (failure modes)
- elongation strength of single fibre measured by air jet

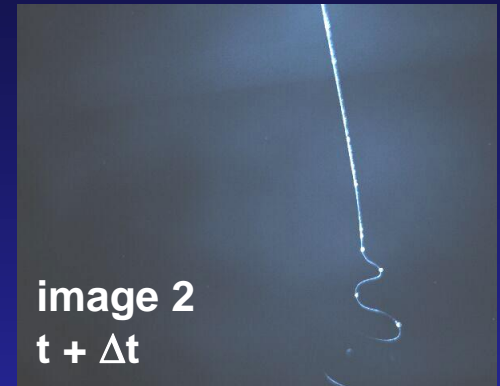
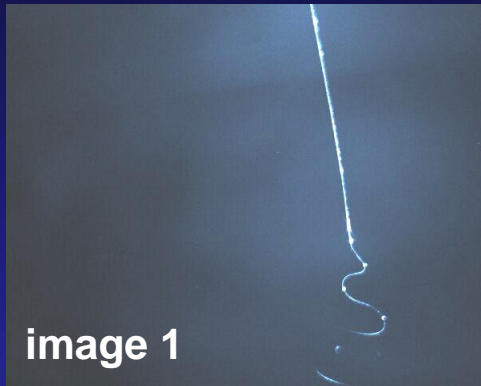


Effect of

- Electrostatic potential V
- Distance pipette-collector H
- Solution concentration c
- Distance from the pipette x



Parametric study

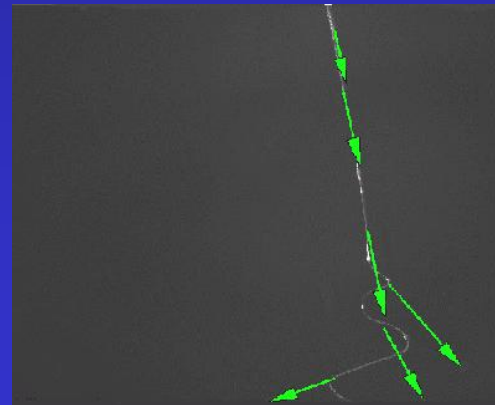


PIV

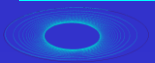
cross – correlation

$\Delta t = 500 \mu s$

- concentration of PEO: 3%
- Voltage: 8 kV
- $H = 215 \text{ mm}$
- polymer solution with the addition of fluorescent particles ($0.3 \mu m$ polymer microspheres)
- light source: Nd:Yag laser

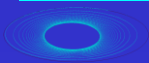


Average
velocity of the
fibres: 2 m/s

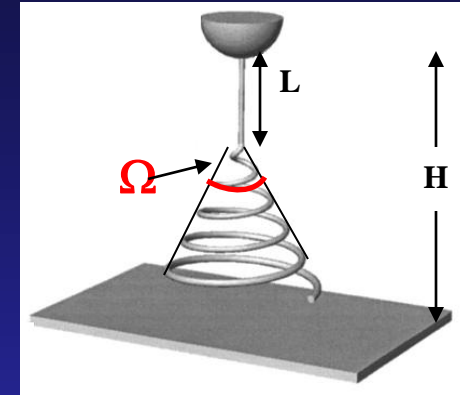
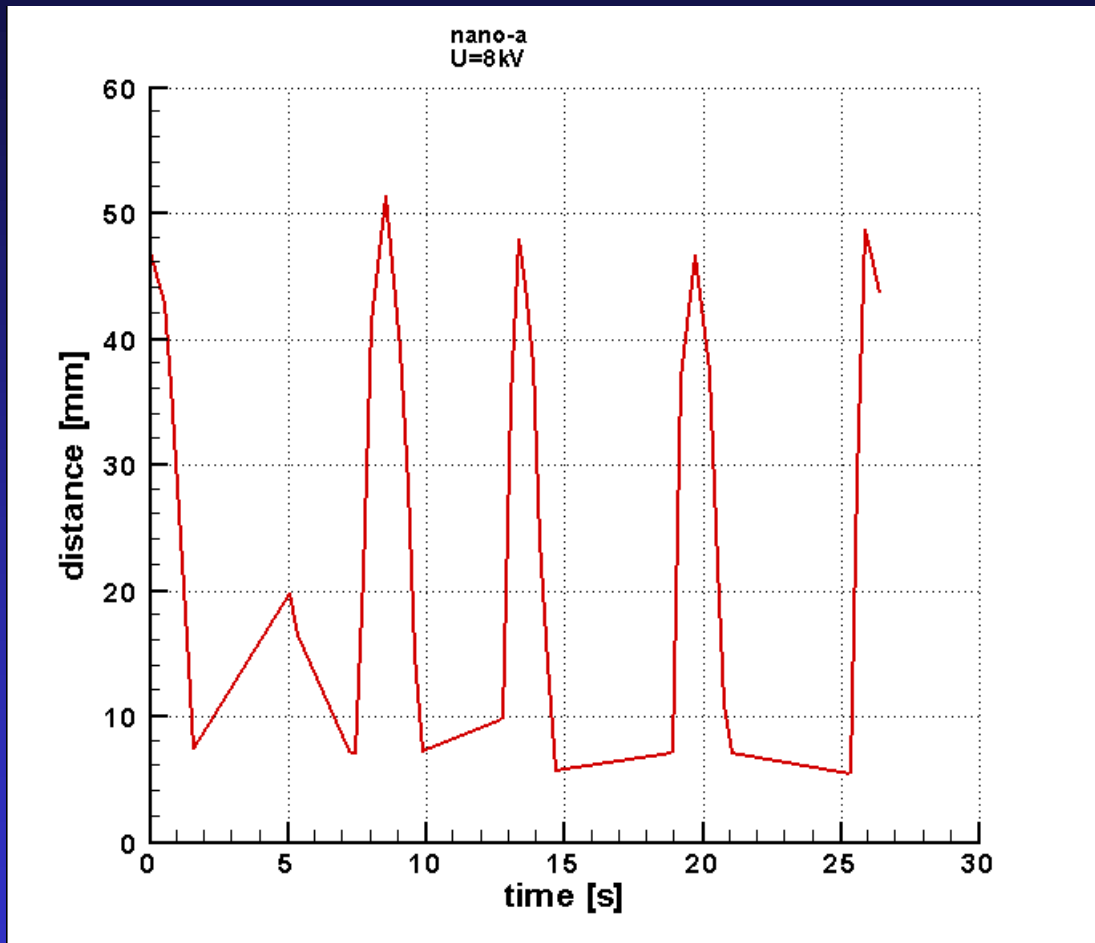


Tested polymers

Test	Polymer	Solvent	Concentration	Voltage [kV]	Electrospinning
I	PEO poly(ethylene oxide)	40% water 60% ethanol mixture	3 – 4 %	3 – 12	good and stable process for voltage up to 10kV
II	DBC dibutyrylo chitin	ethanol	9 %	6 – 16	fairly good
III	TAC cellulose triacetate	methylo chloride	20 %	3 – 30	polymer too viscous
			7 %	10 – 30	difficult
IV	PAN polyacrylonitrile	dimethyl-formamide (DMF)	15 %	5 – 25	very good
V	Glycerol	water	88 %	20 – 30	difficult, lack of solidification cause that the liquid jet is separated into small droplets (electrospray)



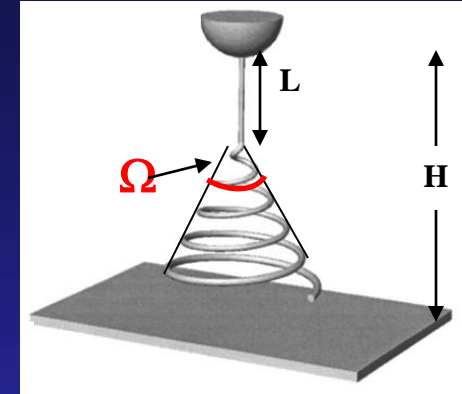
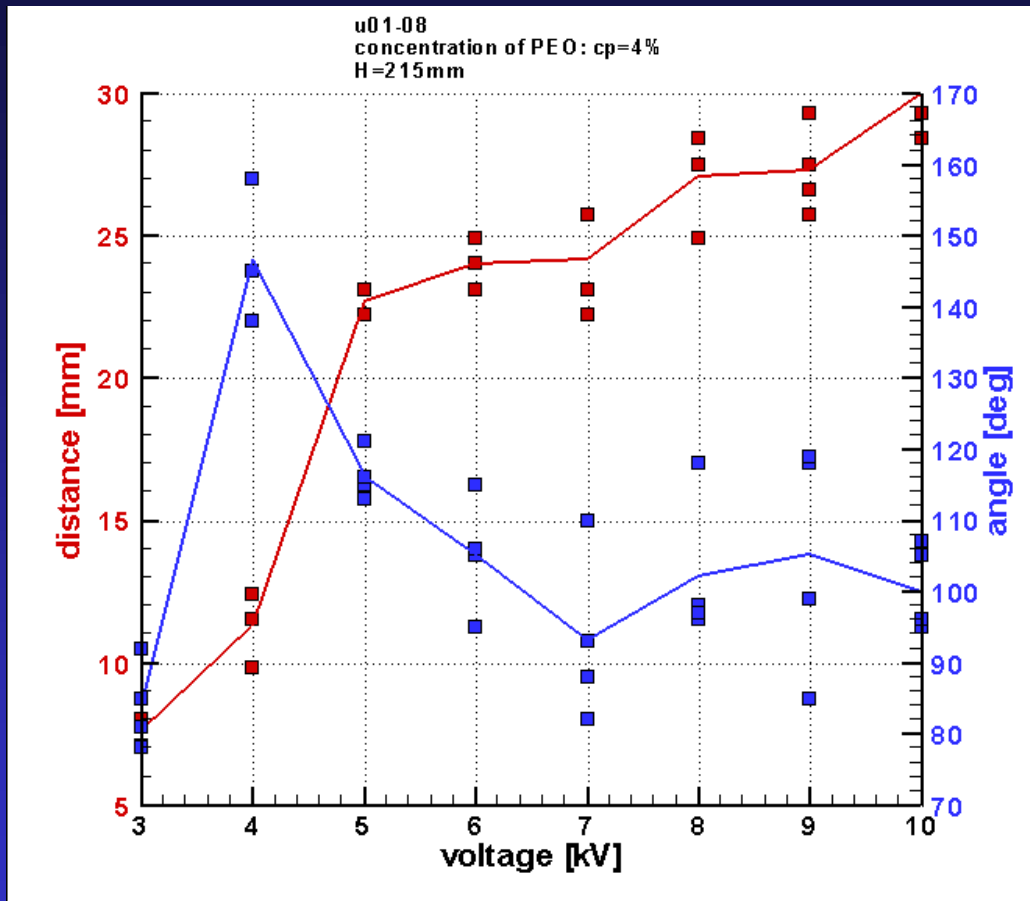
Parametric study



- Polymer: PEO
- Concentration: $c=3\%$
- Solvent: 40% water-ethanol solution
- $H=215\text{mm}$
- $V=8\text{kV}$

➤ $L(t)$ – instability of length of the rectilinear part

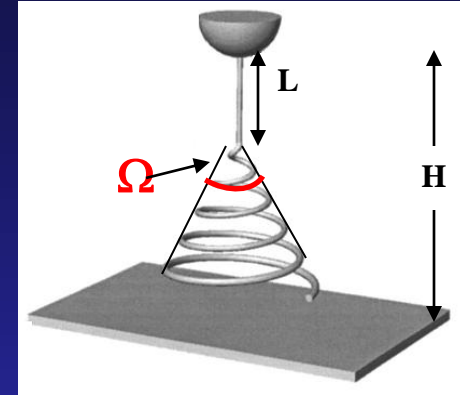
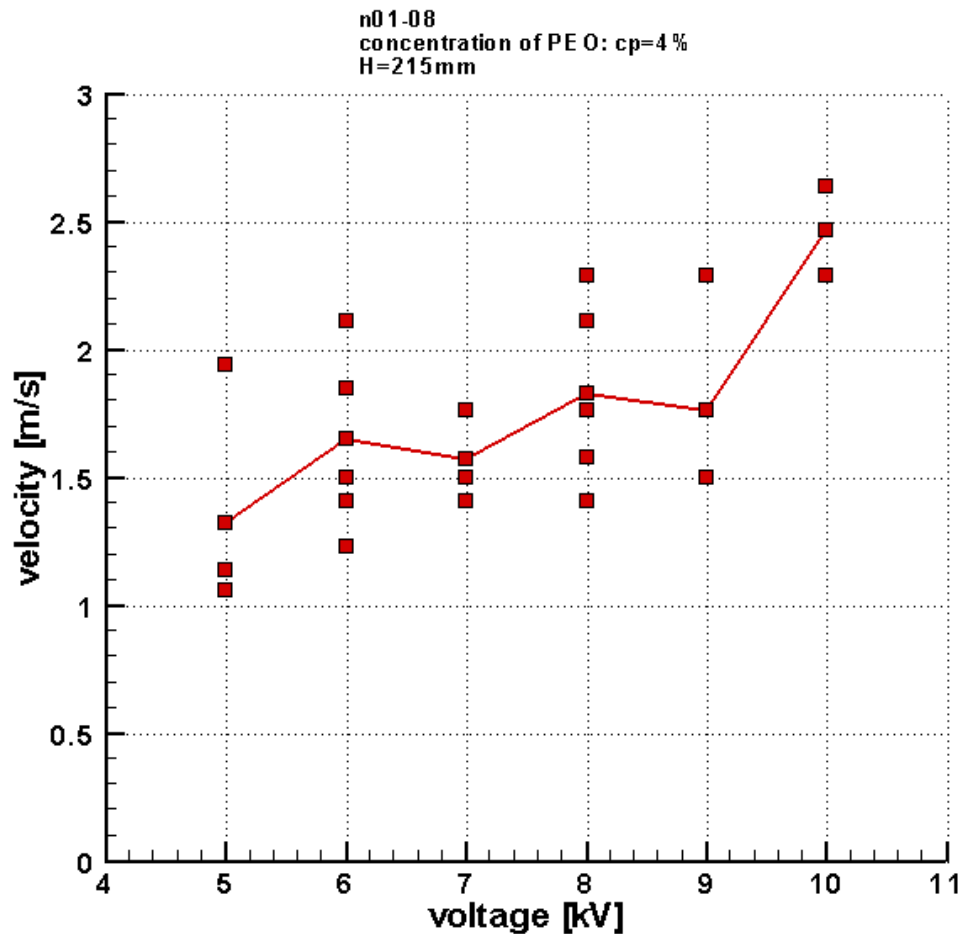
Parametric study



- Polymer: PEO
- Concentration: c=4%
- Solvent: 40% water-ethanol solution
- H=215mm

- L (V) – length of the rectilinear part
- Ω (V) – angle of the envelope cone

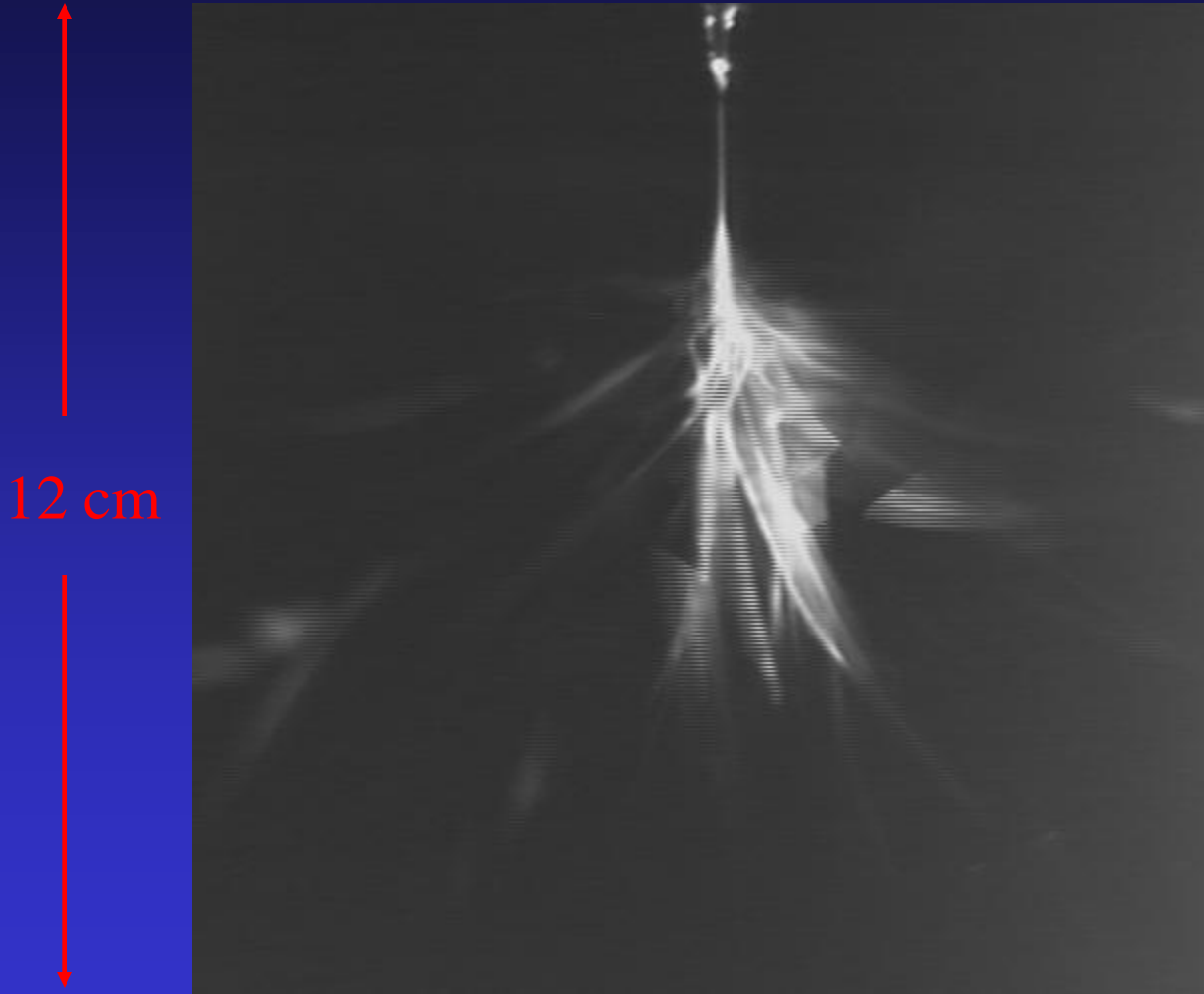
Parametric study



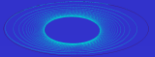
- Polymer: PEO
- Concentration: $c=4\%$
- Solvent: 40% water-ethanol solution
- $H=215\text{mm}$

➤ $U(V)$ – velocity of the fibre at the rectilinear part

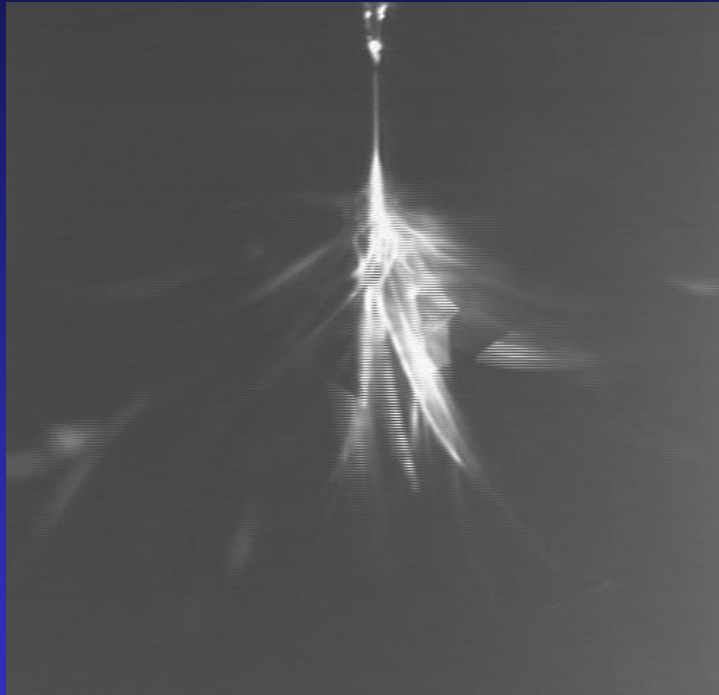
Electrospinning observed at 25fps



- Polymer: DBC
- Concentration: $c=9\%$
- Solvent: ethanol
- $H=215\text{mm}$
- $V=6\text{kV}$



Different structure of spinning fibres for DBC polymer

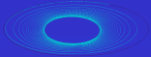


U=6kV

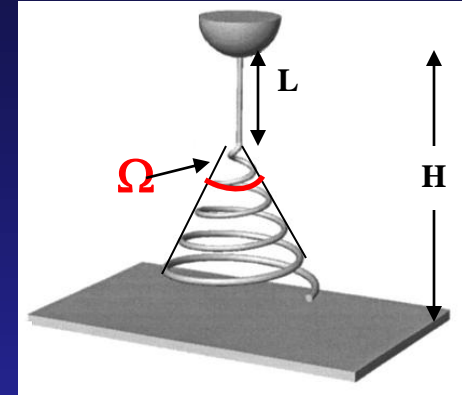
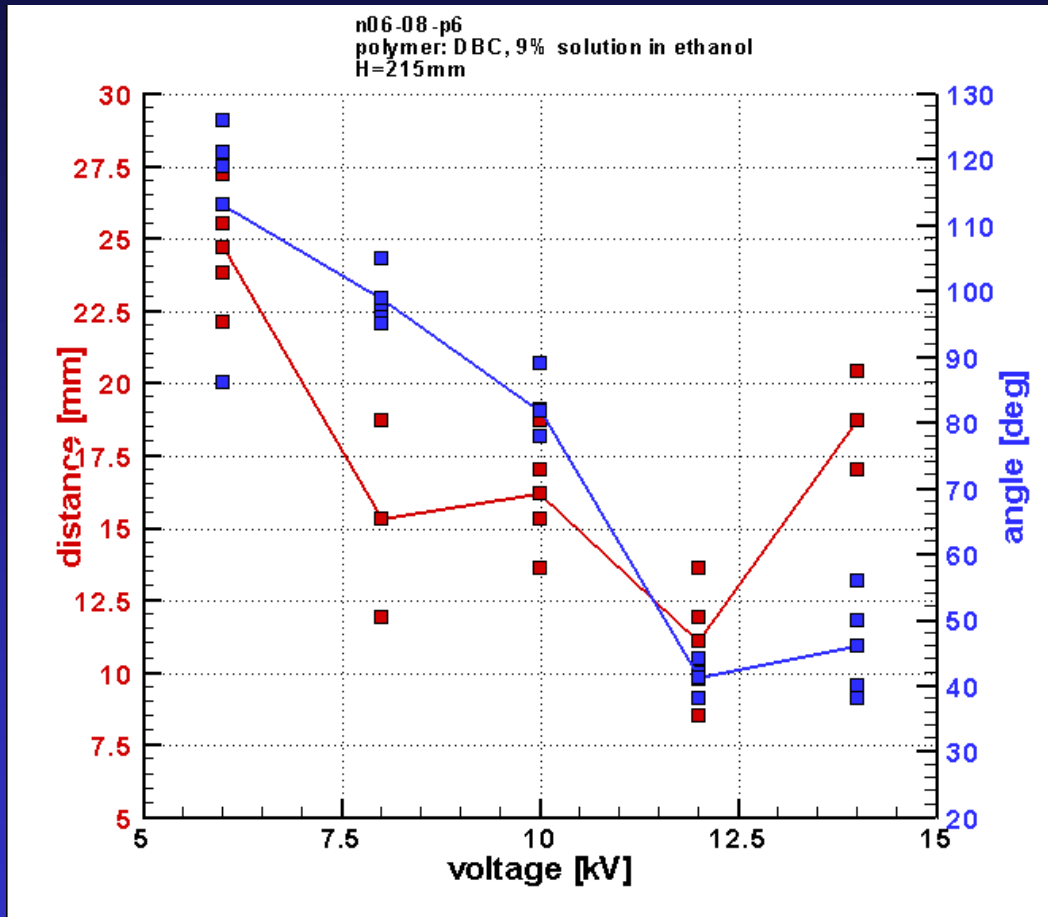


U=12kV

DBC: c=9% H=215mm



Parametric study



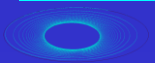
- Polymer: DBC
- Concentration: c=9%
- Solvent: ethanol
- H=215mm

- L (V) – length of the rectilinear part
- Ω (V) – angle of the envelope cone

Electrospinning observed at 25fps



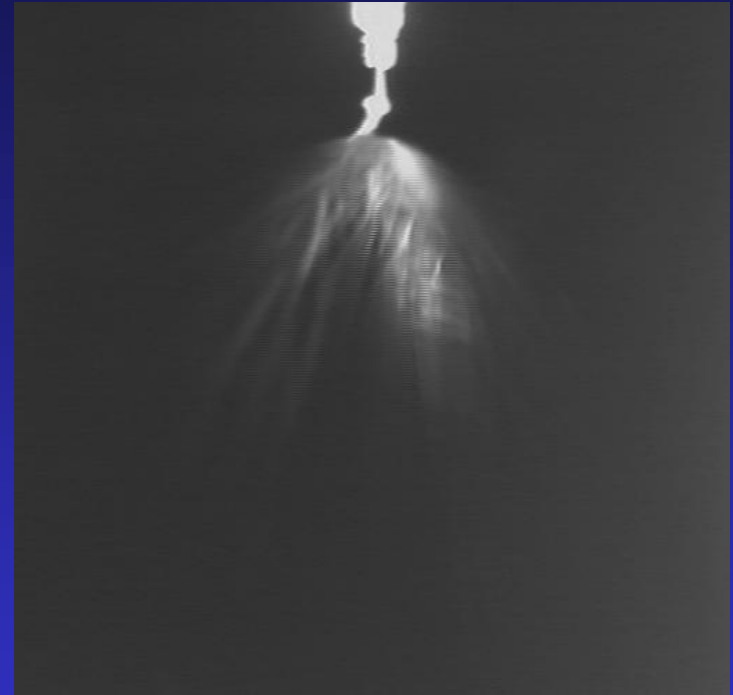
- Polymer: PAN
- Concentration: $c=15\%$
- Solvent: DMF
- $H=215\text{mm}$
- $V=13\text{kV}$



Different structure of spinning fibres for PAN polymer



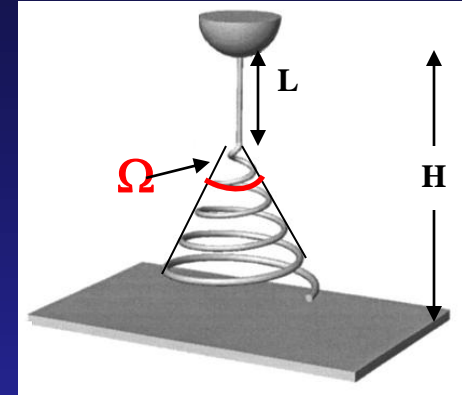
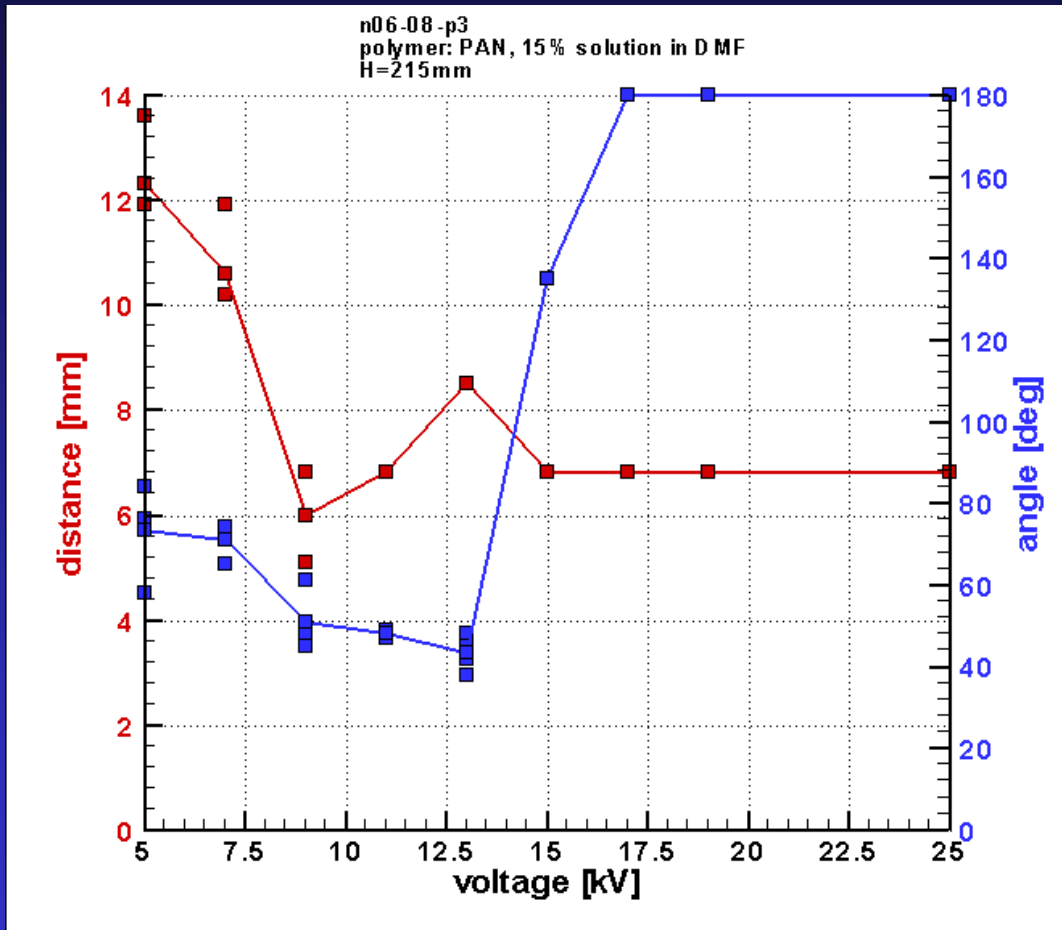
U=13kV



U=19kV

PAN: c=15% H=215mm

Parametric study

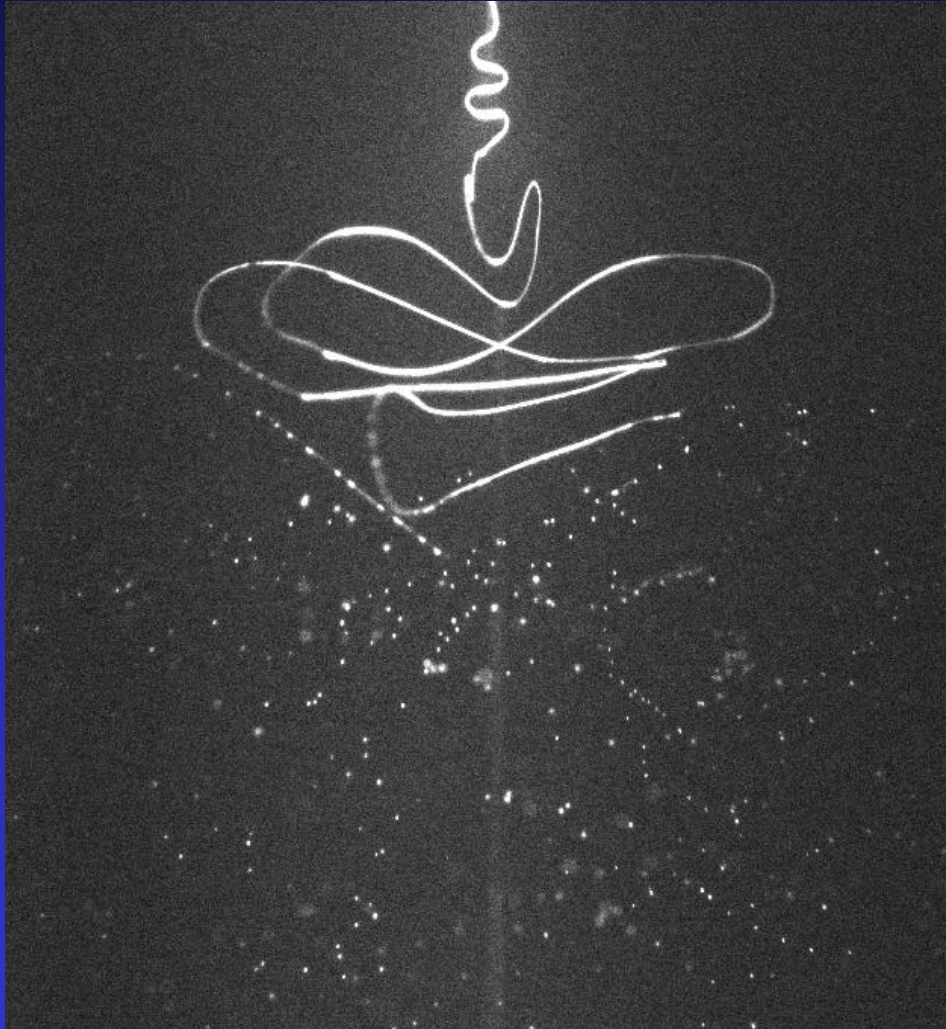


- Polymer: PAN
- Concentration: c=15%
- Solvent: DMF
- H=215mm

- L (V) – length of the rectilinear part
- Ω (V) – angle of the envelope cone

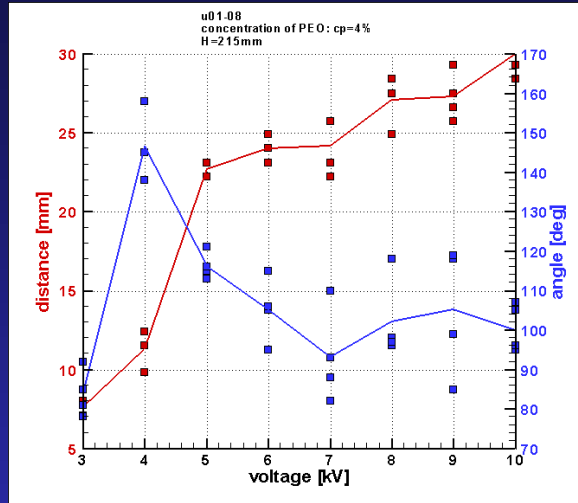
Electrospinning of Glycerol

12 cm

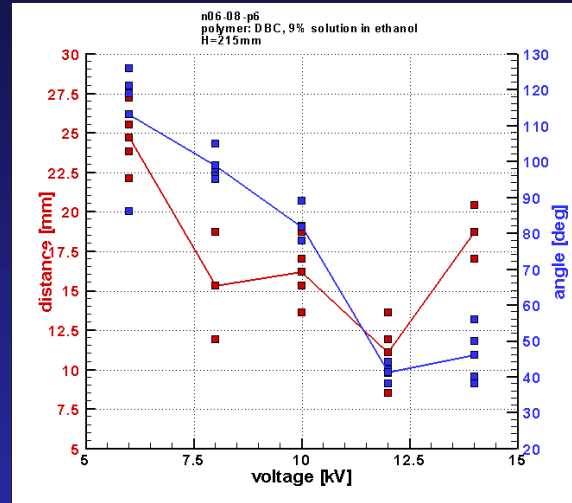


- Glycerol
- Concentration: $c=88\%$
- Solvent: water
- $H=215\text{mm}$
- $V=20\text{kV}$

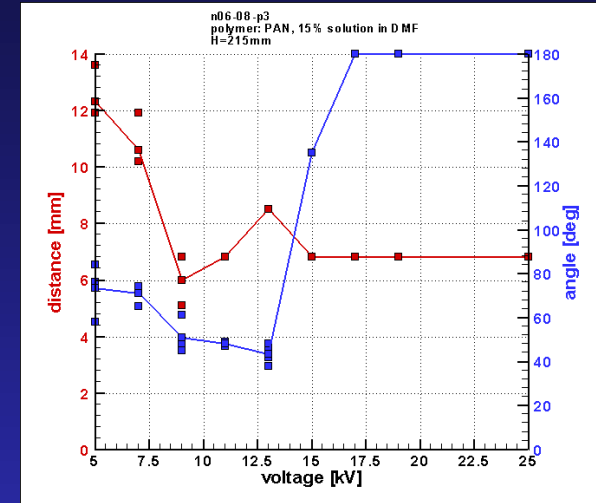
Comparison of PEO & DBC & PAN polymers



PEO



DBC



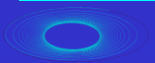
PAN

- L (V) – length of the rectilinear part
- Ω (V) – angle of the envelope cone

Numerical model

Main assumptions

- *The electric field created by the generator is considered static and is approximated using a sphere-plate capacitor configuration*
- *The fibre is a perfect insulator with a constant electric charge density distributed over its surface*
- *The melt is viscoelastic and has constant elastic modulus, viscosity and surface tension*



Numerical model

2. Governing equations

□ *Mass conservation:*

$$\frac{D}{Dt} (\lambda \pi a^2) = 0$$

□ *Stress balance*

$$\frac{\partial \sigma}{\partial t} = G \frac{1}{\lambda} \frac{\partial \lambda}{\partial t} - \frac{G}{\mu} \sigma$$

□ *Momentum balance*

$$\begin{aligned} \rho \lambda \pi a^2 \frac{D\mathbf{V}}{Dt} = & \lambda \pi a^2 \int q^2 \lambda(s^*) \pi a^2(s^*) C \left(\frac{a}{|\mathbf{r} - \mathbf{r}(s^*)|} \right) \frac{\mathbf{r} - \mathbf{r}(s^*)}{|\mathbf{r} - \mathbf{r}(s^*)|^3} ds^* + \lambda \pi a^2 q \mathbf{E} \\ & + \frac{\partial}{\partial s} (\pi a^2 \sigma \mathbf{u}) \\ & + \frac{\partial}{\partial s} (\pi a \alpha \mathbf{u}) \end{aligned}$$

α – surface tension

λ – stretching parameter (relative elongation)

μ – viscosity

ρ – density

σ – longitudinal stress

a – radius of the fiber

C – short-range E-field cutoff factor

\mathbf{E} – electric field

G – elastic modulus

q – charge per unit length

\mathbf{r} – coordinate vector

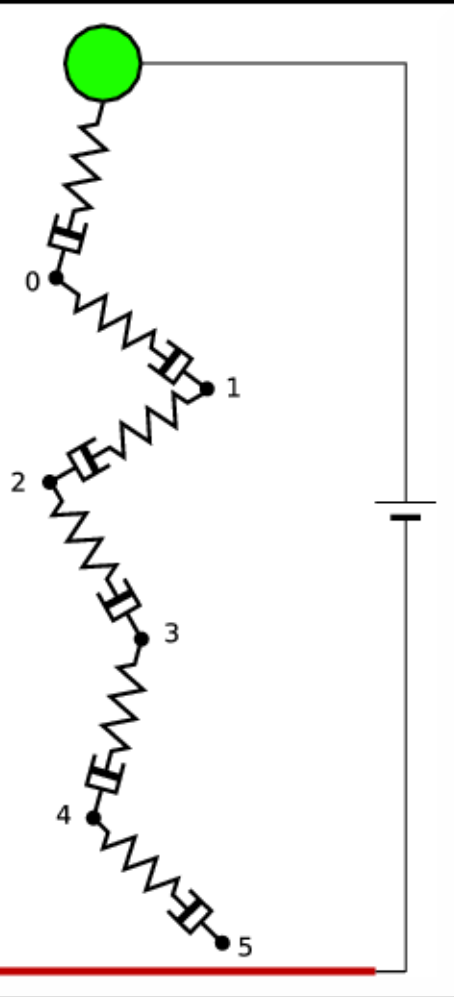
s – Lagrangian curvilinear coordinate

\mathbf{u} – unit vector along the fiber

\mathbf{V} – velocity vector

Numerical model

3. Discretized equations



□ **Mass conservation:**

$$\frac{d}{dt} \left(\pi |\mathbf{r}_i - \mathbf{r}_{i+1}| a_{i,i+1}^2 \right) = 0$$

□ **Stress balance**

$$\frac{d\sigma_{i,i+1}}{dt} = G \frac{(\mathbf{r}_{i+1} - \mathbf{r}_i) (\mathbf{V}_{i+1} - \mathbf{V}_i)}{(\mathbf{r}_{i+1} - \mathbf{r}_i)^2} - \frac{G}{\mu} \sigma_{i,i+1}$$

□ **Momentum balance**

$$\begin{aligned} m_i \frac{d\mathbf{V}_i}{dt} = & q_i \sum_{j \neq i} q_j C_{i,j} \frac{\mathbf{r}_i - \mathbf{r}_j}{|\mathbf{r}_i - \mathbf{r}_j|^3} + q_i \mathbf{E} \\ & + \pi a_{i,i+1}^2 \sigma_{i,i+1} \frac{\mathbf{r}_{i+1} - \mathbf{r}_i}{|\mathbf{r}_{i+1} - \mathbf{r}_i|} - \pi a_{i-1,i}^2 \sigma_{i-1,i} \frac{\mathbf{r}_i - \mathbf{r}_{i-1}}{|\mathbf{r}_i - \mathbf{r}_{i-1}|} \\ & + \pi a_{i,i+1} \alpha \frac{\mathbf{r}_{i+1} - \mathbf{r}_i}{|\mathbf{r}_{i+1} - \mathbf{r}_i|} - \pi a_{i-1,i} \alpha \frac{\mathbf{r}_i - \mathbf{r}_{i-1}}{|\mathbf{r}_i - \mathbf{r}_{i-1}|} \end{aligned}$$

Numerical model

4. Boundary conditions

The last particle introduced at the tips keeps a constant velocity until the distance to the tip exceeds the initial bead length l_0 :

$$\mathbf{V}_0 == -\frac{Q}{\pi a_0^2} \mathbf{z} \quad \text{for } |\mathbf{r}_0 - \mathbf{r}_{\text{tip}}| \leq l_0$$

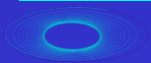
l_0 – initial bead length [input]
 Q – volume flow rate [input]

A small perturbation is added to the position of each new particle introduced near the tip:

$$\begin{aligned} x_0 &= x_{\text{tip}} + \epsilon \sin \varphi \\ y_0 &= y_{\text{tip}} + \epsilon \cos \varphi \end{aligned}$$

ϵ – distance to the main axis [input]
 φ – random phase

Particles that reach the collector are considered neutralized and are removed from the fibre.



Numerical model

5. Parametric simulations

Reference case:

$$\alpha = 0.07 \text{ N/m}$$

$$\Phi = 5000 \text{ V}$$

$$\mu = 10 \text{ Pa.s}$$

$$G = 10^5 \text{ Pa}$$

$$\rho = 1000 \text{ kg/m}^3$$

$$a_0 = 150 \text{ }\mu\text{m}$$

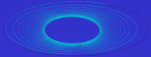
$$H = 20 \text{ cm}$$

$$l_0 = 1 \text{ }\mu\text{m}$$

$$q = 200 \text{ C/m}^3$$

$$Q = 3.6 \text{ cm}^3/\text{h}$$

Case	α	Φ	μ	G
1	3			
2	/3			
3		x2		
4			x5	
5				x2
6				/2



Numerical model

Reference case:

$$\alpha = 0.07 \text{ N/m}$$

$$\Phi = 5000 \text{ V}$$

$$\mu = 10 \text{ Pa.s}$$

$$G = 10^5 \text{ Pa}$$

$$\rho = 1000 \text{ kg/m}^3$$

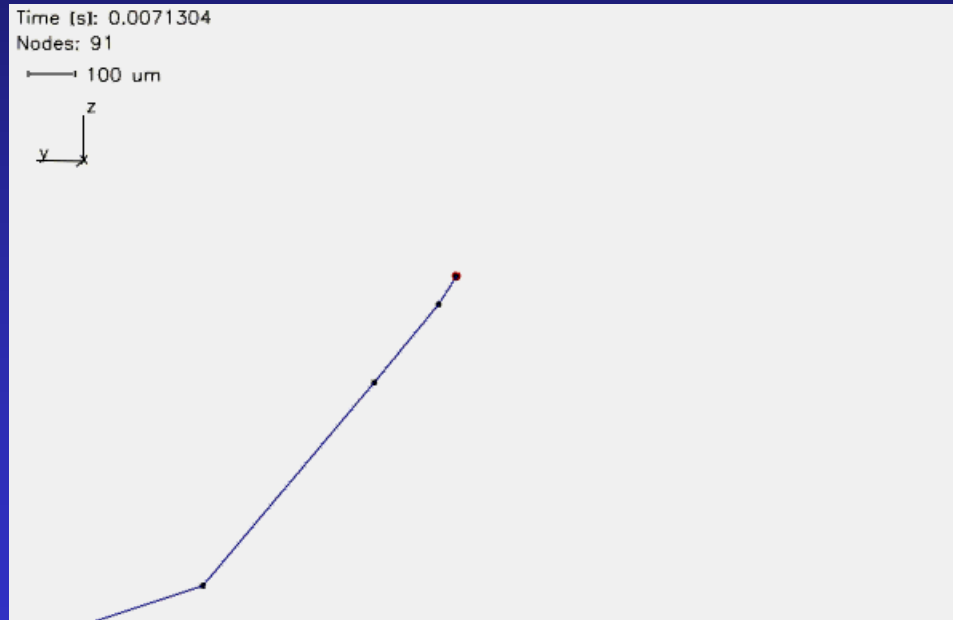
$$a_0 = 150 \text{ }\mu\text{m}$$

$$H = 20 \text{ cm}$$

$$l_0 = 1 \text{ }\mu\text{m}$$

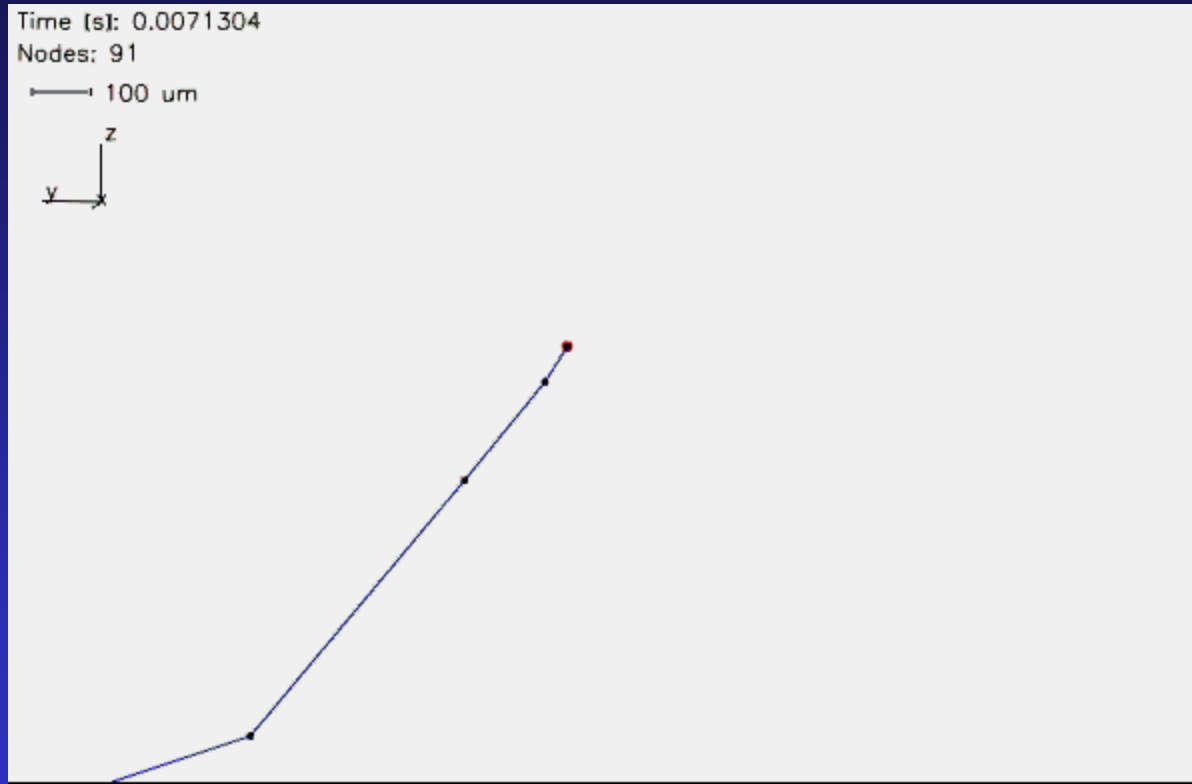
$$q = 200 \text{ C/m}^3$$

$$Q = 3.6 \text{ cm}^3/\text{h}$$



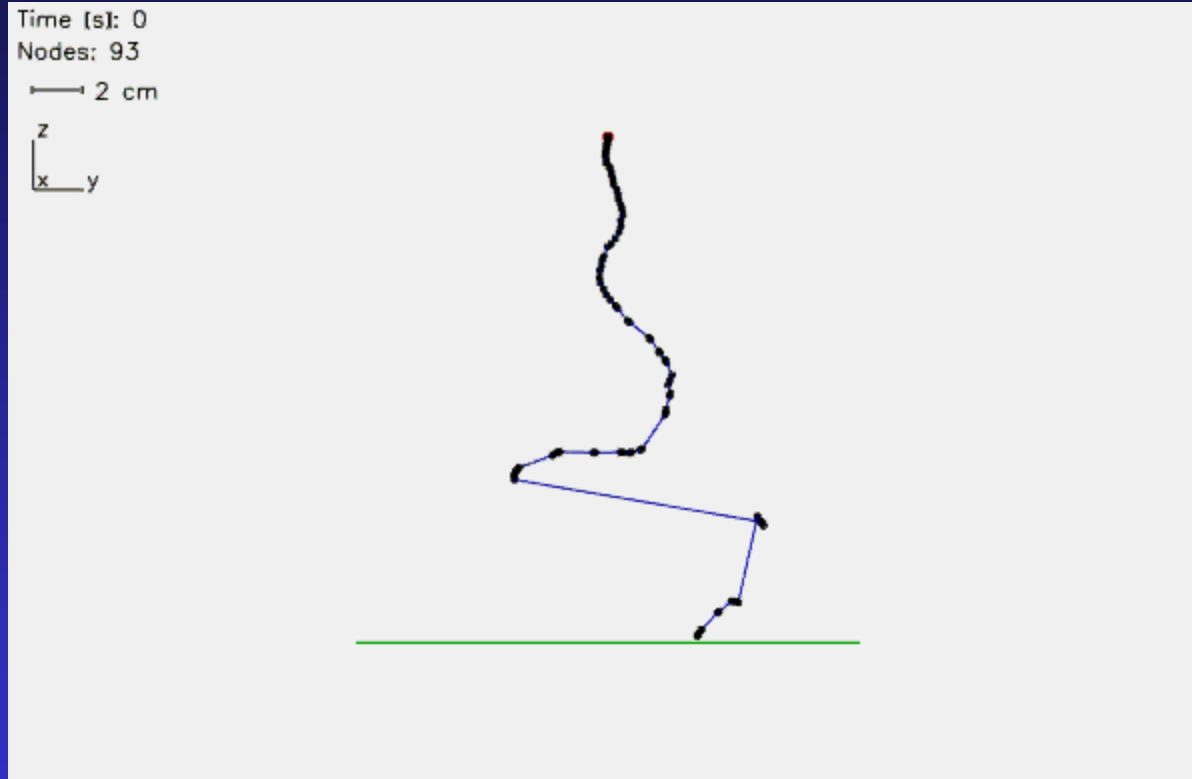
Numerical model

Reference case



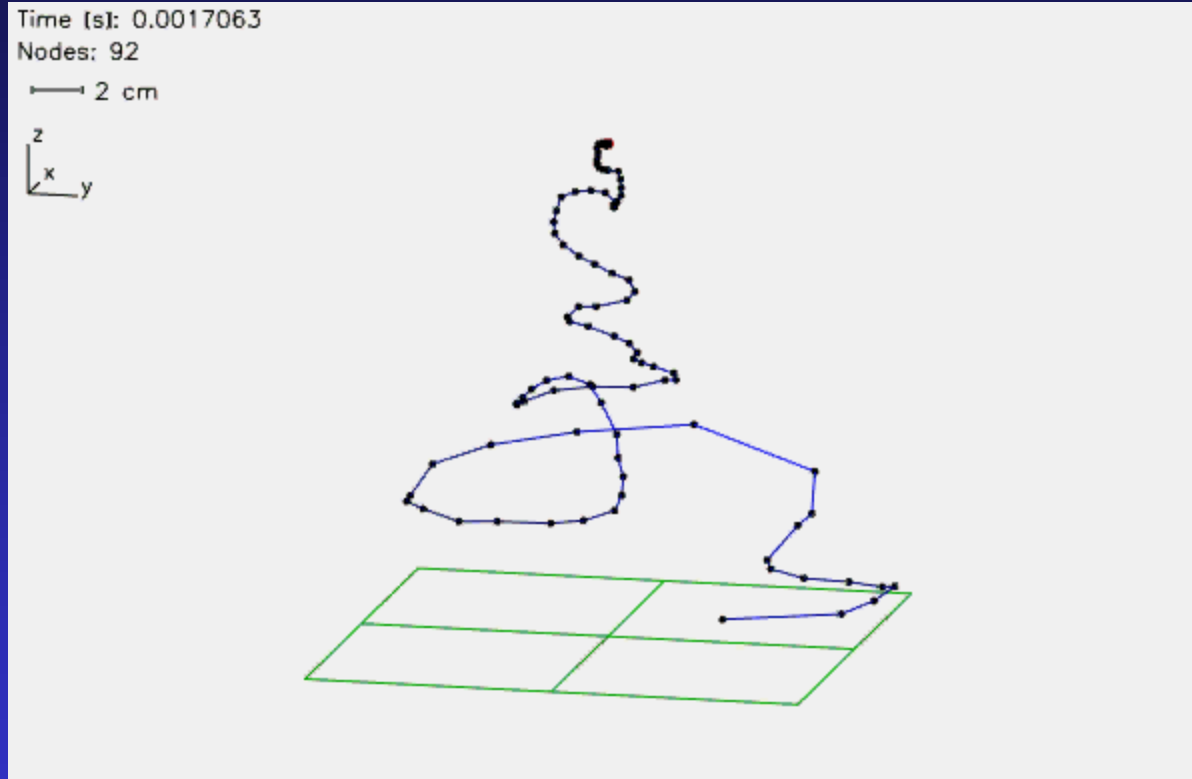
Numerical model

Triple surface tension



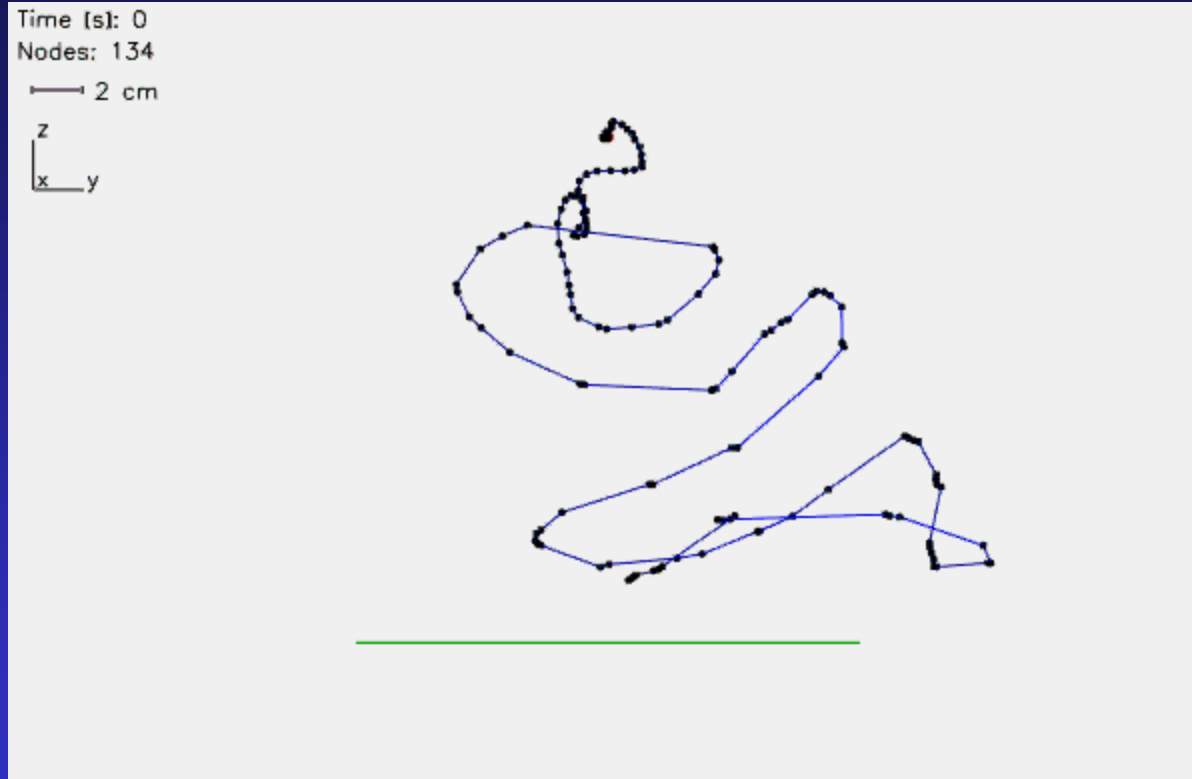
Numerical model

1/3 surface tension



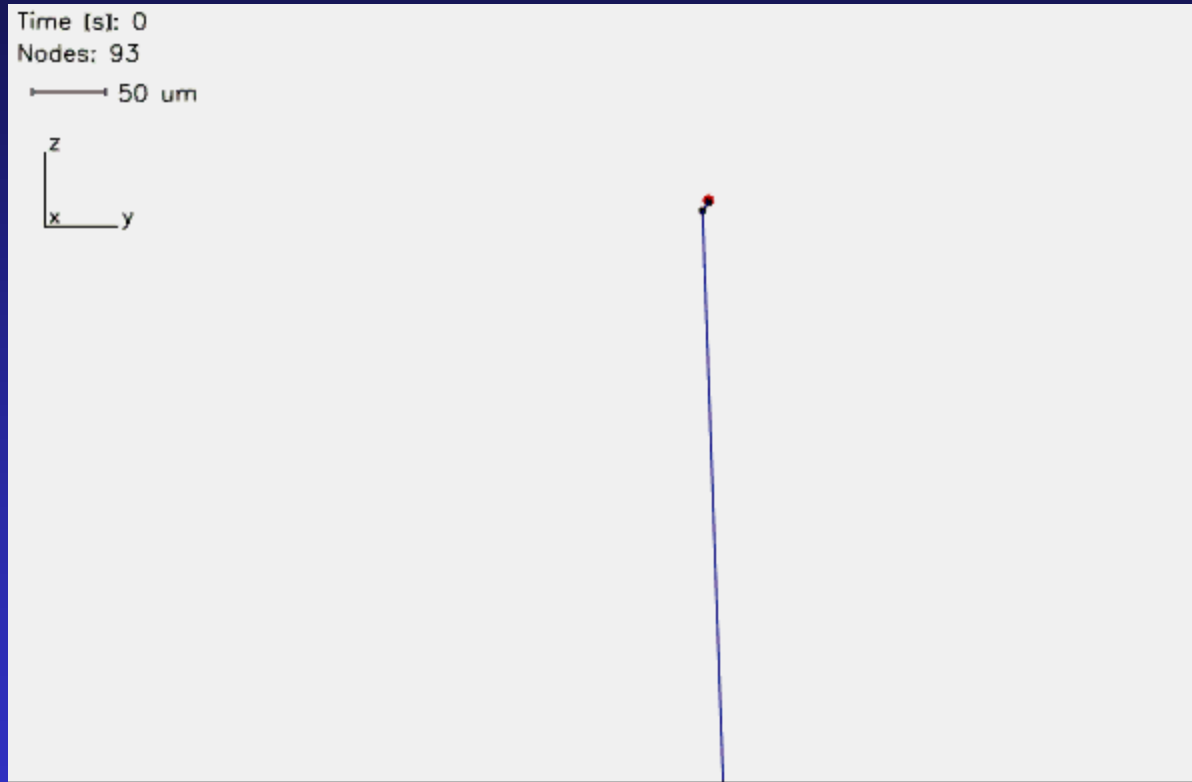
Numerical model

$\frac{1}{2}$ Voltage



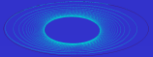
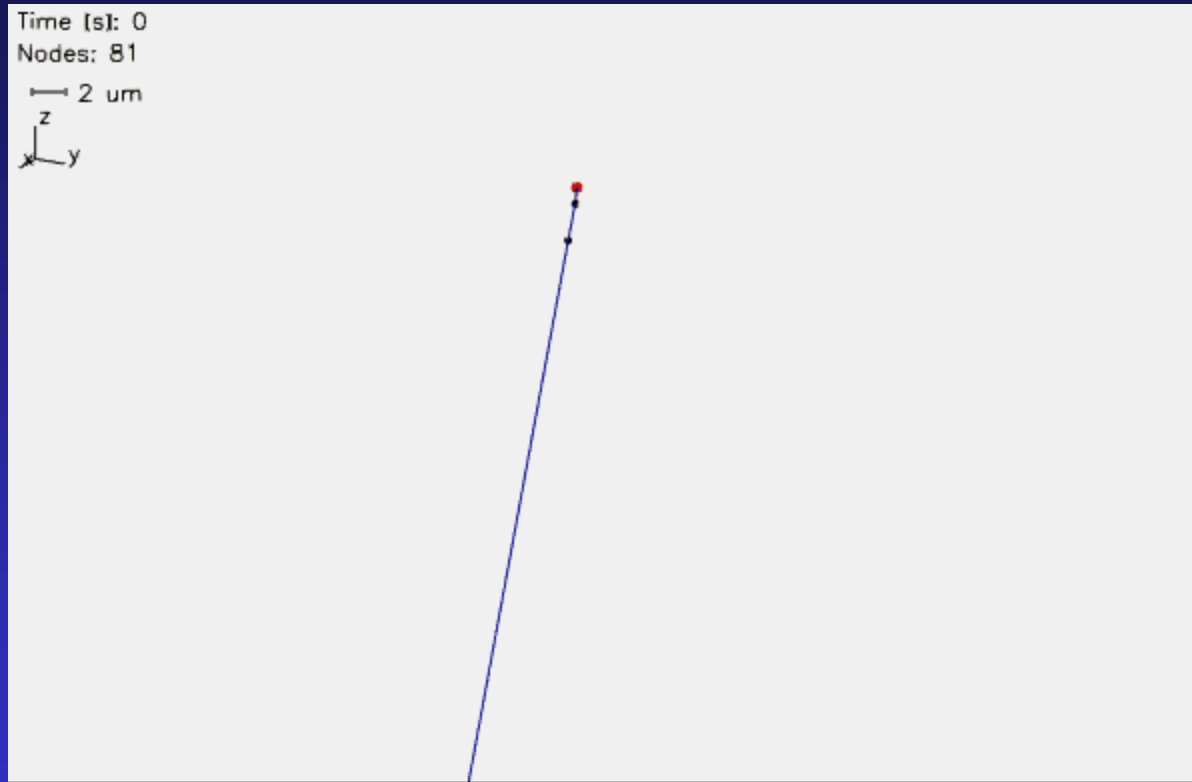
Numerical model

5 times higher viscosity



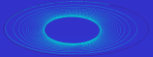
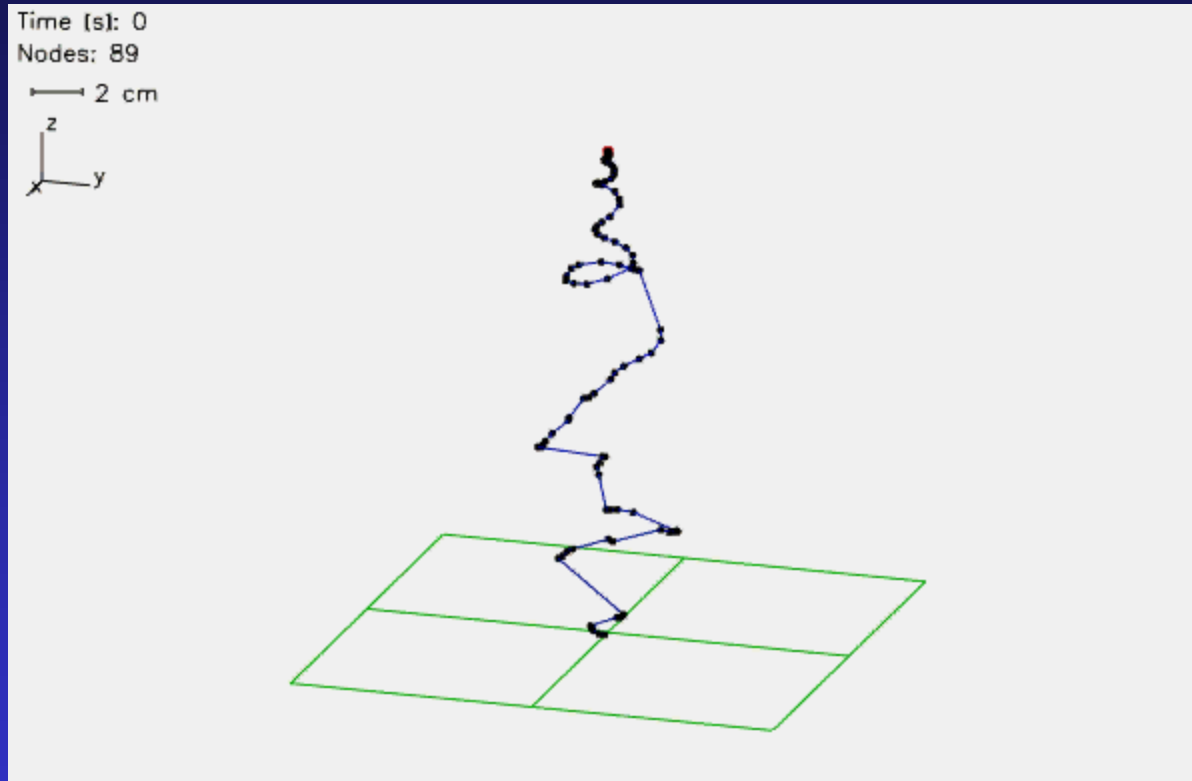
Numerical model

Double elastic modulus



Numerical model

Half elastic modulus



Numerical model

$$\alpha = 0.07 \text{ N/m}$$

$$\Phi = 5000 \text{ V}$$

$$\mu = 10 \text{ Pa.s}$$

$$G = 10^5 \text{ Pa}$$

$$\rho = 1000 \text{ kg/m}^3$$

$$a_0 = 150 \text{ }\mu\text{m}$$

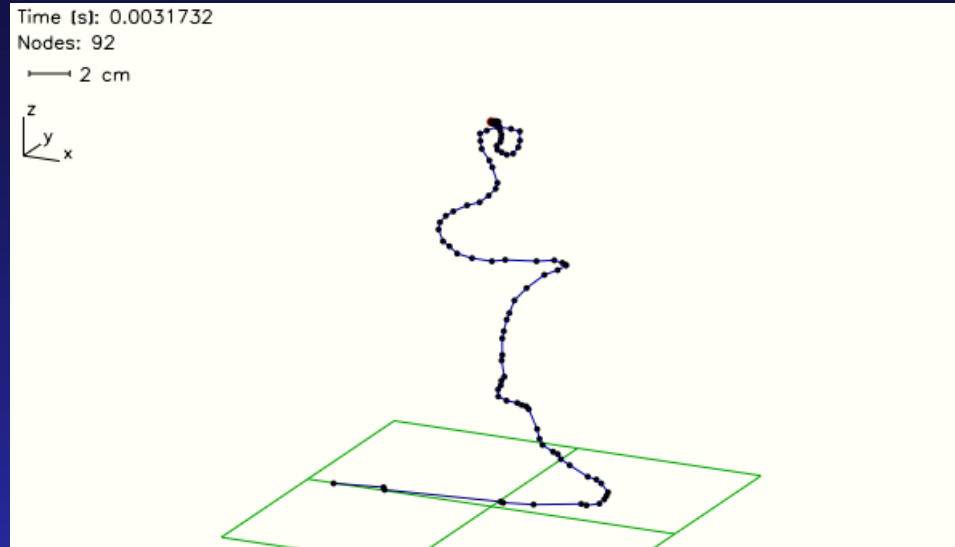
$$H = 20 \text{ cm}$$

$$l_0 = 1 \text{ }\mu\text{m}$$

$$q = 200 \text{ C/m}^3$$

$$Q = 3.6 \text{ cm}^3/\text{h}$$

Reference case:

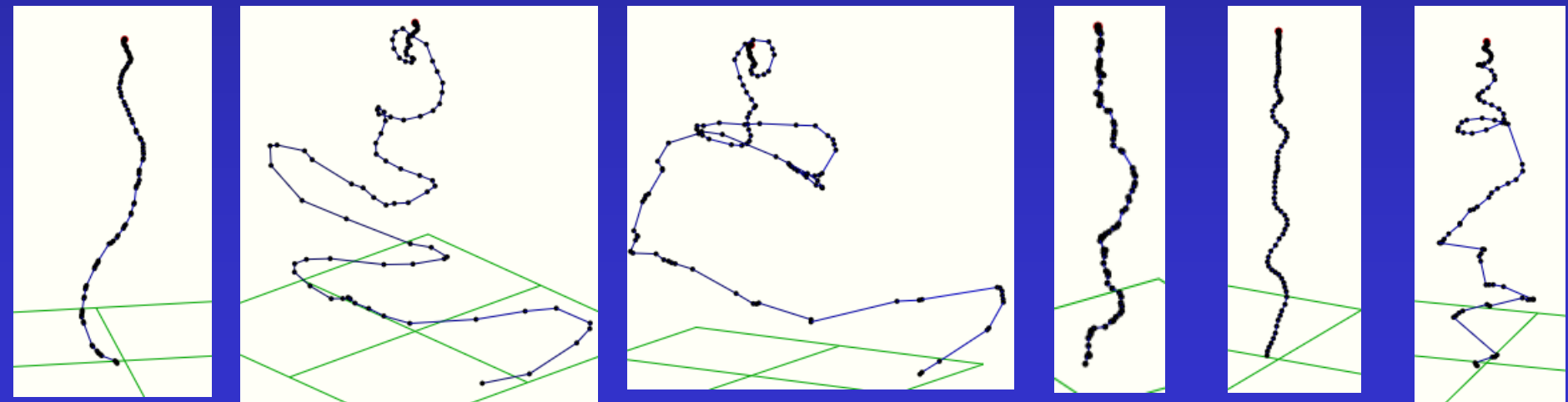


$$\alpha = 0.21 \text{ N/m}$$

$$\alpha = 0.023 \text{ N/m}$$

$$\Phi = 2500 \text{ V}$$

$$\mu = 2 \text{ Pa.s} \quad G = 2 \cdot 10^5 \text{ Pa} \quad G = 5 \cdot 10^4 \text{ Pa}$$



Conclusions

- ✓ **Electrostatic elongation of polymer threads allows to produce relatively easily fibres in nano range diameters**
- ✓ **Collection of nano-woven of bio-active polymers, e.g.. chitin may have practical application for tissue growth**
- ✓ **Simulations recover some key physical phenomena but fail at modelling the straight jet portion**
- ✓ **The modeling of electrospun fibers is still embryonic. Improvements are required in many areas:**
 - better physical description (evaporation, varying viscosity, ...)
 - checking of the mathematical correctness of the model (is the discrete charge model fully consistent?)
 - development of a fast algorithm for Coulomb interactions

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We would like to acknowledge the valuable contribution of dr Anna Błasińska from TU of Łódź and Anna Blim from IPPT PAN in the work presented.

