

Stability and Break-up of Jets of Viscoelastic Fluids

Kick-Off Meeting CONEX Project

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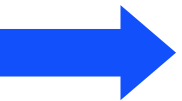
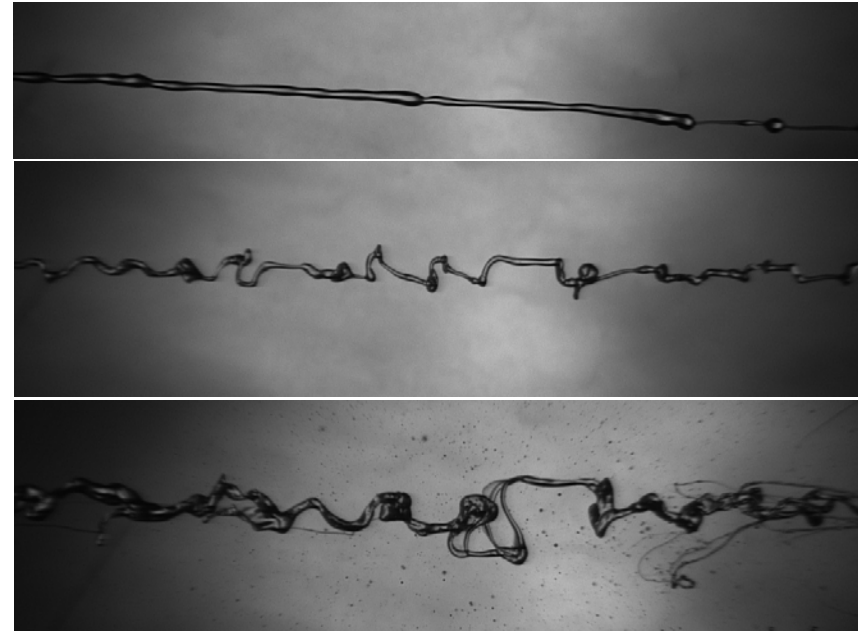
Contents of the Presentation

- Motivation and aims
- Linear temporal stability analysis
- Validation of the dispersion relation
- Limitations of linear theories
 - Growth rates, break-up lengths
 - Break-up mechanisms
- Generalised Ohnesorge nomogram
- Summary and conclusions



Motivation and Aims

- Break-up of viscoelastic liquid jets is an important process
- Stability behaviour is to be investigated
- Onset of different break-up mechanisms is of interest



Generalisation of the Ohnesorge jet break-up nomogram is attempted

Linear Stability Analysis - Basic Equations

Continuity
$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \mathbf{v} = 0$$

Momentum
$$\left(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right) \rho \mathbf{v} = -\nabla \cdot \pi + \rho \mathbf{g}$$

where
$$\pi = p\delta + \tau$$

Rheological constitutive equation - Oldroyd model

$$\begin{aligned} \tau + \lambda_1 \frac{D\tau}{Dt} + \frac{1}{2} \mu_0 (tr \tau) \dot{\gamma} - \frac{1}{2} \mu_1 \{ \tau \cdot \dot{\gamma} + \dot{\gamma} \cdot \tau \} + \frac{1}{2} \nu_1 (\tau : \dot{\gamma}) \delta \\ = -\eta_0 [\dot{\gamma} + \lambda_2 \frac{D\dot{\gamma}}{Dt} - \mu_2 \{ \dot{\gamma} \cdot \dot{\gamma} \} + \frac{1}{2} \nu_2 (\dot{\gamma} : \dot{\gamma}) \delta] \end{aligned}$$

(G. Brenn et al., IJMF vol. 26 (2000), 1621-1644)



Linearised Equations for Incompressible Fluid

Continuity

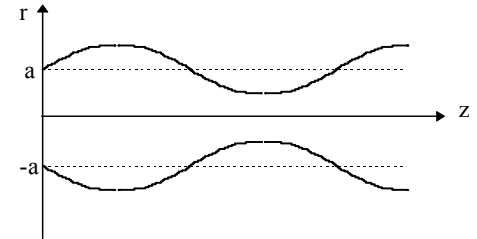
$$\nabla \cdot \mathbf{v} = 0$$

Momentum

$$\rho \left(\frac{\partial}{\partial t} + \bar{U} \frac{\partial}{\partial x} \right) \mathbf{v} = -\nabla \cdot (p\delta + \boldsymbol{\tau})$$

Rheology

$$\boldsymbol{\tau} + \lambda_1 \left(\frac{\partial}{\partial t} + \bar{U} \frac{\partial}{\partial x} \right) \boldsymbol{\tau} = -\eta_0 [\dot{\gamma} + \lambda_2 \left(\frac{\partial}{\partial t} + \bar{U} \frac{\partial}{\partial x} \right) \dot{\gamma}]$$



Boundary conditions

- **Linearised form (cylindrical coordinates)**

$$v_r = \left(\frac{\partial}{\partial t} + \bar{U} \cdot \nabla \right) \xi$$

$$v_r = \frac{\partial \xi}{\partial t} + \bar{U} \frac{\partial \xi}{\partial z} \quad r = a$$

$$(\boldsymbol{\pi} - \boldsymbol{\pi}_g) \times \mathbf{n} = 0$$

$$\pi_{rz} = \tau_{rz} = -\eta(\alpha) \left(\frac{\partial v_z}{\partial r} + \frac{\partial v_r}{\partial z} \right) = 0 \quad r = a$$

$$(\boldsymbol{\pi} - \boldsymbol{\pi}_g) \cdot \mathbf{n} + \sigma \nabla \cdot \mathbf{n} = 0$$

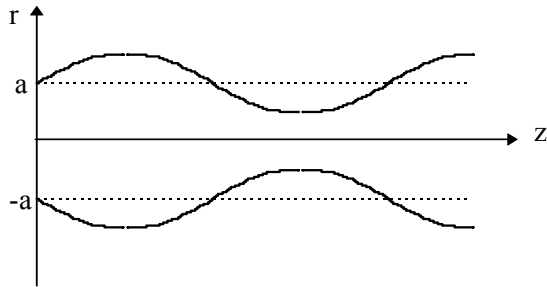
$$\pi_{rr} - \pi_{g,rr} + p_\sigma = 0 \quad r = a$$



Wave Solution and Dispersion Relation

We seek solutions in the form of moving waves

$$\phi = \Phi(r)e^{ikz + \alpha t}$$



k - real wave number

α - complex frequency

real part - disturbance growth rate

imaginary part - frequency

The same procedure is applied to the gas phase also, but the gas treated as inviscid. Expressing the normal stresses in the liquid and in the gas in terms of the above results:



Dispersion relation emerges

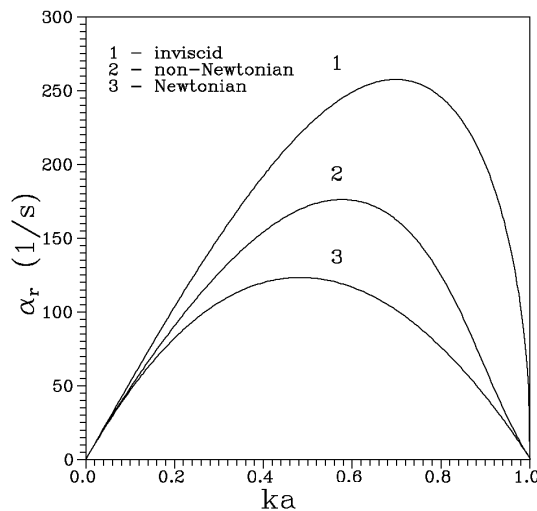


Dispersion relation for viscoelastic jet

Disturbance growth rate as a function of the non-dimensional wavenumber

$$\alpha^2 \left[\frac{ka}{2} \frac{I_0(ka)}{I_1(ka)} + \frac{ka}{2} \frac{\rho_g}{\rho} \frac{K_0(ka)}{K_1(ka)} \right] + \alpha \left\{ 2ik\bar{U}_R \frac{ka}{2} \frac{\rho_g}{\rho} \frac{K_0(ka)}{K_1(ka)} + \frac{\eta_0}{\rho a^2} \frac{1 + \lambda_2(\alpha + ik\bar{U}_R)}{1 + \lambda_1(\alpha + ik\bar{U}_R)} k^2 a^2 \left[2ka \frac{I_0(ka)}{I_1(ka)} \frac{l^2}{l^2 - k^2} - 1 - 2la \frac{I_0(la)}{I_1(la)} \frac{k^2}{l^2 - k^2} \right] \right\}$$

frequency dependent viscosity



$$= \frac{\sigma}{2\rho a^3} k^2 a^2 (1 - k^2 a^2) + C \cdot \frac{\rho_g}{\rho} \frac{\bar{U}_R^2}{2a^2} k^3 a^3 \frac{K_0(ka)}{K_1(ka)}$$

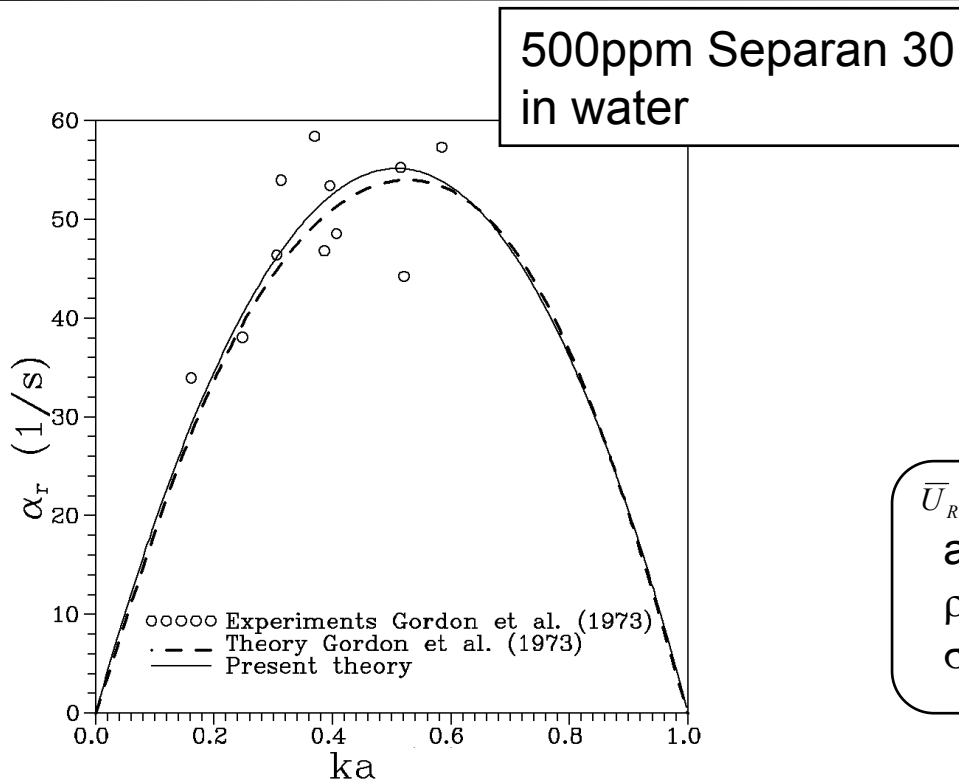
capillary influence

$$\begin{aligned} \bar{U}_R &= 2\text{m/s} & \eta_0 &= 0.1\text{Pa}\cdot\text{s} \\ a &= 500\mu\text{m} & \lambda_1 &= 10\text{ms} \\ \rho &= 1000\text{kg/m}^3 & \lambda_2 &= 1\text{ms} \\ \rho_g &= 1.2\text{kg/m}^3 & (Z=0.535, \\ \sigma &= 70\text{mN/m} & \text{We}=28.6) \end{aligned}$$

aerodynamic influence

$$(C = 0.175)$$

Validation of the Theory - I



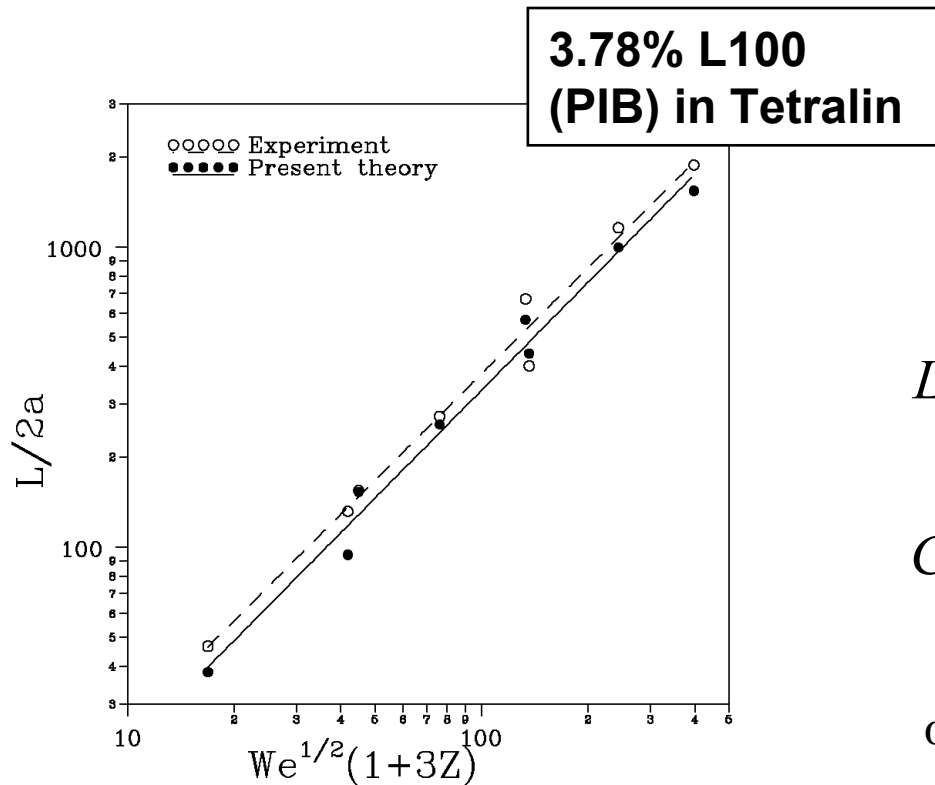
Aqueous
polyacrylamide
solution

$$\begin{aligned}\bar{U}_R &= 0 & \eta_0 &= 0.11 \text{ Pa}\cdot\text{s} \\ a &= 921 \mu\text{m} & \lambda_1 &= 0.1 \text{ ms} \\ \rho &= 1000 \text{ kg/m}^3 & \lambda_2 &= 0.01 \text{ ms} \\ \sigma &= 70 \text{ mN/m} & (Z &= 0.431)\end{aligned}$$

**Growth rate = $f(ka)$ from present theory and experiments /
theory by Gordon et al. (1973) - good agreement**



Validation of the Theory - II



Organic polyisobutylene solution

$$L / 2a = C_1 \frac{U}{2a\alpha^*} = C_1 \sqrt{We}(1 + 3Z)$$

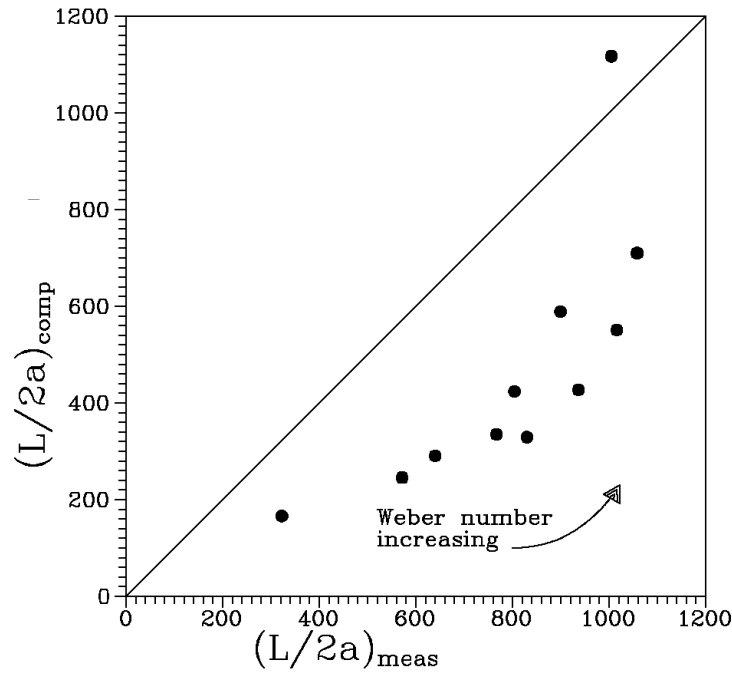
$$C_1 = \frac{C_2}{1 + 3El / (1 + 3Z)^2} ; \quad C_2 \approx 12$$

α^* from the present theory

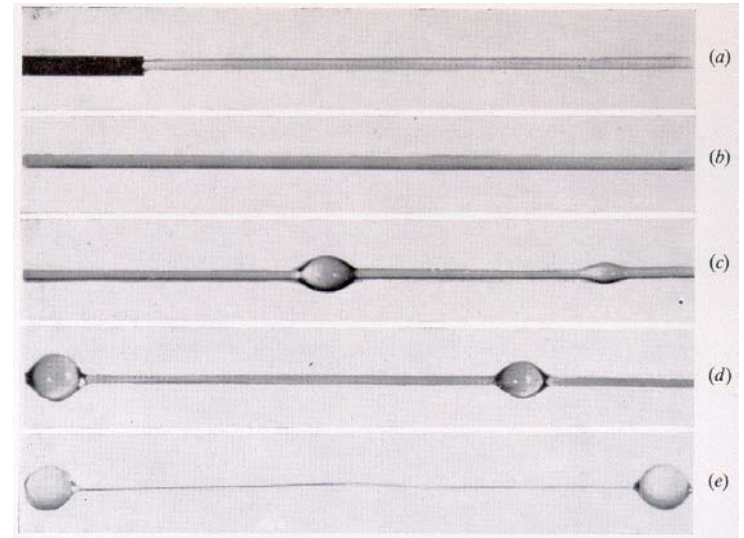
Break-up length by Kroesser and Middleman (1969) and from present theory using coefficients C_1 from Kroesser and Middleman



Validation of the Theory - III



$$L/2a = C_1 \frac{U}{2a\alpha^*} \quad ; \quad C_1 = 12$$
$$9 \leq We \leq 407$$



Photograph by Goldin et al., JFM 38 (1969)

Linear calculation underestimates the break-up length. Strong nonlinear retardation in the late stages



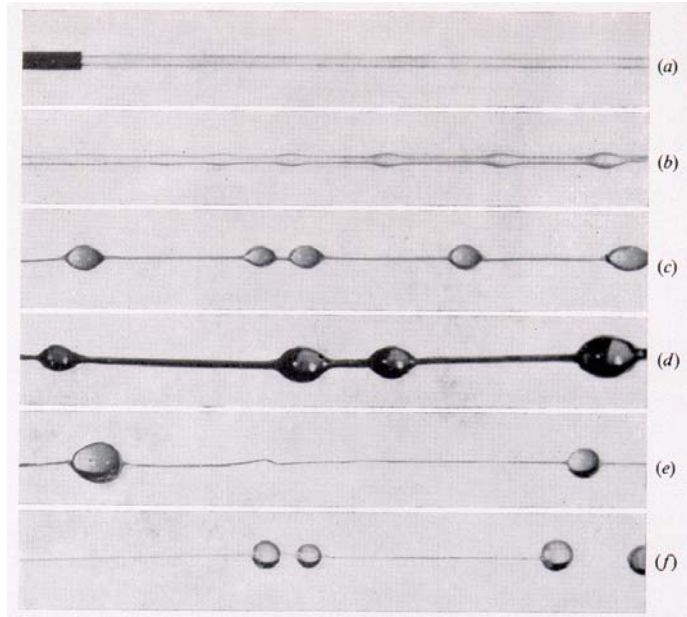
Don't calculate break-up lengths with the linear theory



Break-up Mechanisms

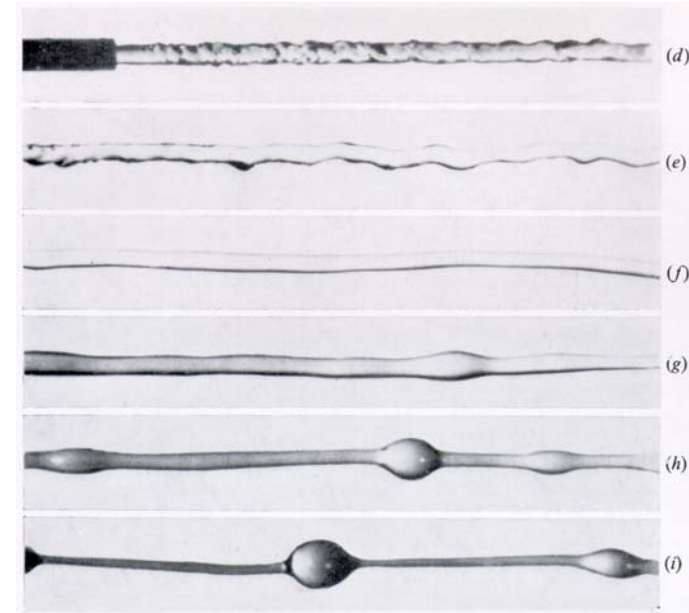
Symmetric deformations

We = 50.2, 500ppm Separan



Antimetric deformations

We = 295, 500ppm Separan



Bending instability (antimetric deformations; Yarin 1993)

$$\gamma^2 + \frac{3}{4} \frac{\chi^4}{\rho a^2} \frac{\mu}{1 + \gamma \lambda_1} \gamma + \chi^2 \left(\frac{\sigma}{\rho a^3} - \frac{\rho_G}{\rho} \frac{\bar{U}_R^2}{a^2} + \frac{T_{zz}}{\rho a^2} \right) = 0$$

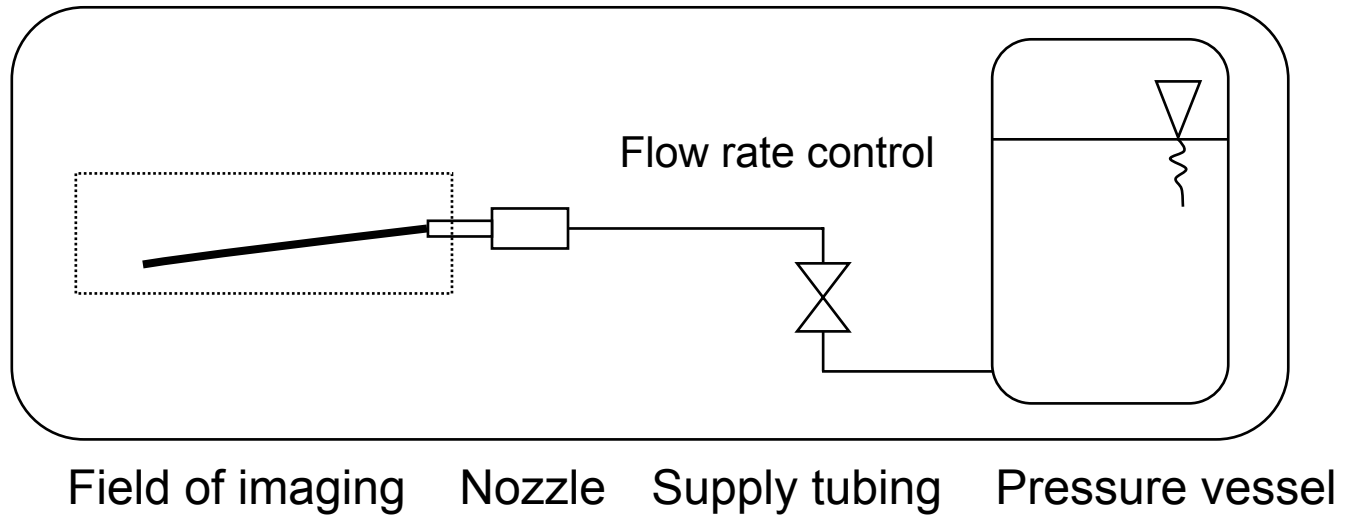
Onset of bending instability $\gamma > 0 \Leftrightarrow We > \frac{\rho}{\rho_G} \left(1 + \frac{T_{zz} a}{\sigma} \right); \Rightarrow We_{ons} = O(10^3)$

(Photographs by Goldin et al., JFM 38 (1969), pp. 689-711)



Break-up Mechanisms for viscoelastic jets

Experimental setup used for investigation of viscoelastic jet breakup mechanisms - similar to A. Haenlein's apparatus from 1931

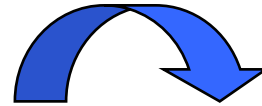


Nozzle:	$L/d = 10$, $d = 0.5, 1$, and 2 mm
Liquids:	Water and aqueous PAM solutions in three concentrations
Flow rates:	$2.6 - 360$ l/h



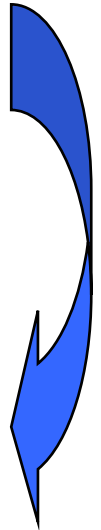
Elongational Rheometer $\Rightarrow$ Theoretical basics

Cylindrical liquid
thread of infinite
length



Viscous Elastic

 Capillary
forces



Thread
diameter

Elongational
viscosity

Stretching
rate

Deborah
number

Viscoelastic

$$d = d_0 e^{-t/3\Theta}$$

$$\mu_{el} = \frac{3\sigma\Theta}{d}$$

$$\dot{\epsilon} = \frac{2}{3\Theta}$$

$$De = \frac{2}{3}$$

Newtonian

$$d = d_0 - \frac{\sigma}{\mu_{el}} t$$

$$\mu_{el} = 3\mu$$

$$\dot{\epsilon} = \frac{2\sigma}{3\mu d}$$

Temporal diameter decrease



Elongational
behaviour

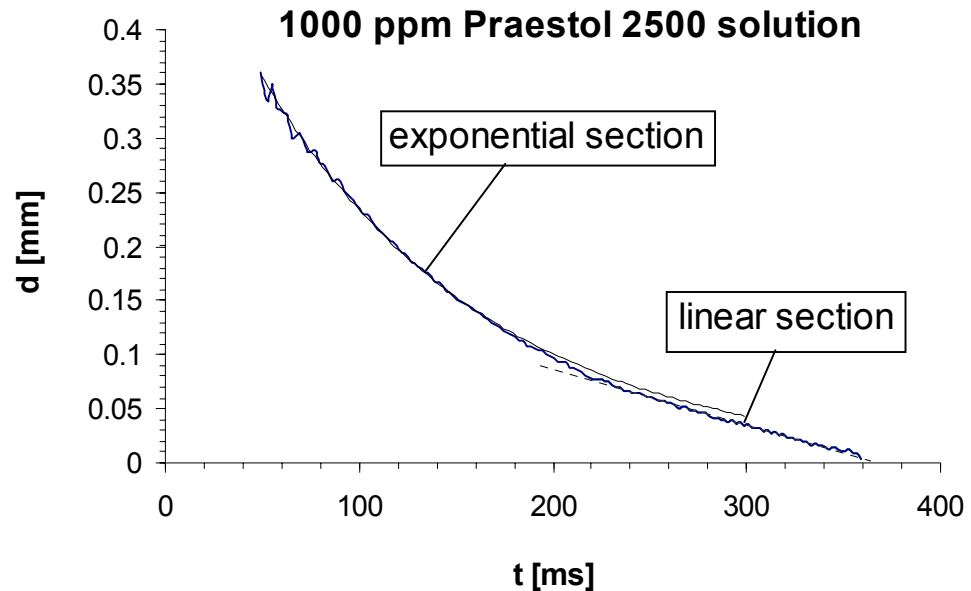


Measurement of Elongational Behaviour

Liquid thread



1000 ppm Praestol
2540 solution



viscoelastic
behaviour



relaxation time



transient elongational
viscosity

quasi-Newtonian
behaviour



steady terminal
elongational viscosity



Dimensional Analysis

Relevant parameters $\rightarrow \mu_{el}, \sigma, \rho, U, d_e, D$

$\rightarrow$ Definition of an effective elongational viscosity from the stretching experiments

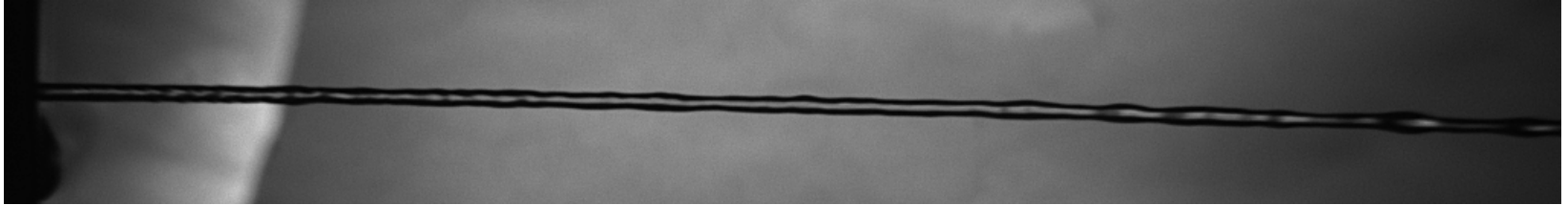
$$\mu_{el,eff} = k \cdot \mu_{el,exp} \cdot De_d \quad \text{where} \quad \mu_{el,exp} = 3\Theta\sigma/d_e \quad \text{and} \quad De_d = \Theta \frac{U}{d_e}$$

- k - empirical parameter to represent results of water and polymer solutions universally
- characteristic for applied flexible/(semi-rigid) and rigid polymers

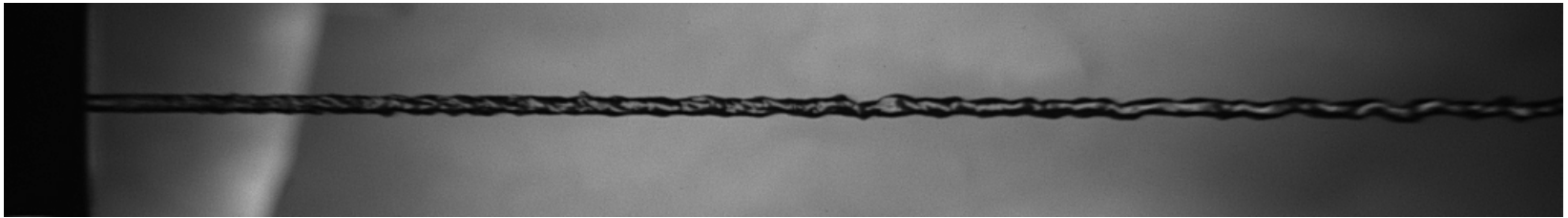
$$\rightarrow \frac{k_{flexible}}{k_{rigid}} = \frac{\left(d\mu_{el,t} / d\Theta \right)_{flexible}}{\left(d\mu_{el,t} / d\Theta \right)_{rigid}}$$



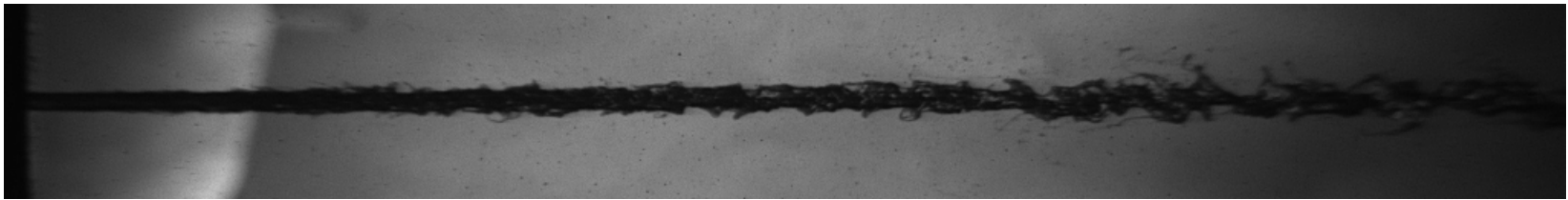
Visualisation of Jet Break-up Mechanisms



100ppm P2500, $V=13$ l/h, $h_{el}=22.5$ mPas, $Re=204$, $We=298$



50ppm P2500, $V=64$ l/h, $h_{el}=11.5$ mPas, $Re=1971$, $We=7216$



50ppm P2500, $V=162$ l/h, $h_{el}=7.2$ mPas, $Re=7962$, $We=46236$

Nozzle $d=2$ mm, aqueous solutions

Direction of flow



Generalised Ohnesorge Jet Break-up Nomogram

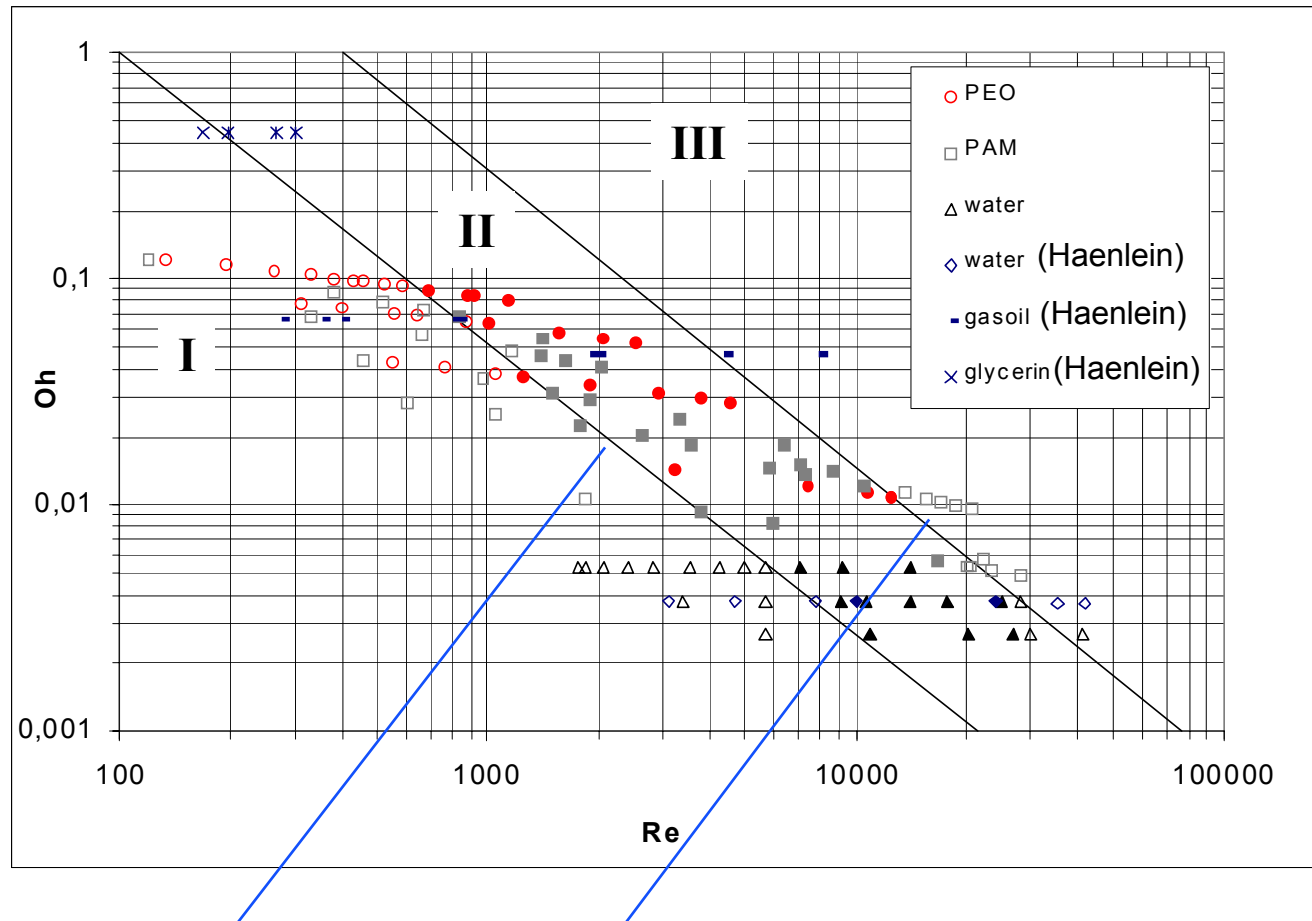
Nomogram
for flexible
polymers and
Newtonians

$$Oh = \eta_{el} / \sqrt{\sigma d \rho}$$

$$Re = Ud\rho / \eta_{el}$$

$$\eta_{el} = k \cdot 3\sigma\theta / d$$

Symbols:
open - I and III
filled - II



$$Oh = 371.7 \cdot Re^{-1.285}$$

$$Oh = 2624.3 \cdot Re^{-1.314}$$

Summary and Conclusions

- A linearised temporal stability analysis of viscoelastic jets has been presented
- The dispersion relation agrees with measured disturbance growth rates at small deformations
- The validity of the jet stability theory is limited by the onset of mechanisms leading to non-axisymmetric deformations and breakup retardation by the polymers
- An experimental survey of the viscoelastic jet break-up mechanisms has resulted in a generalisation of Ohnesorge's jet break-up nomogram

